

Hidden Regular Variation in Joint Tail Modeling with Likelihood Inference via the MCEM Algorithm

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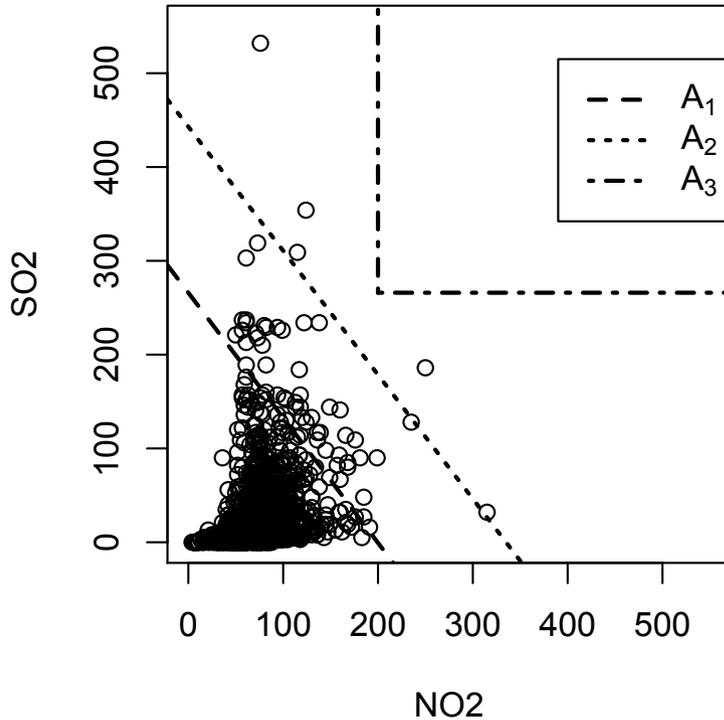
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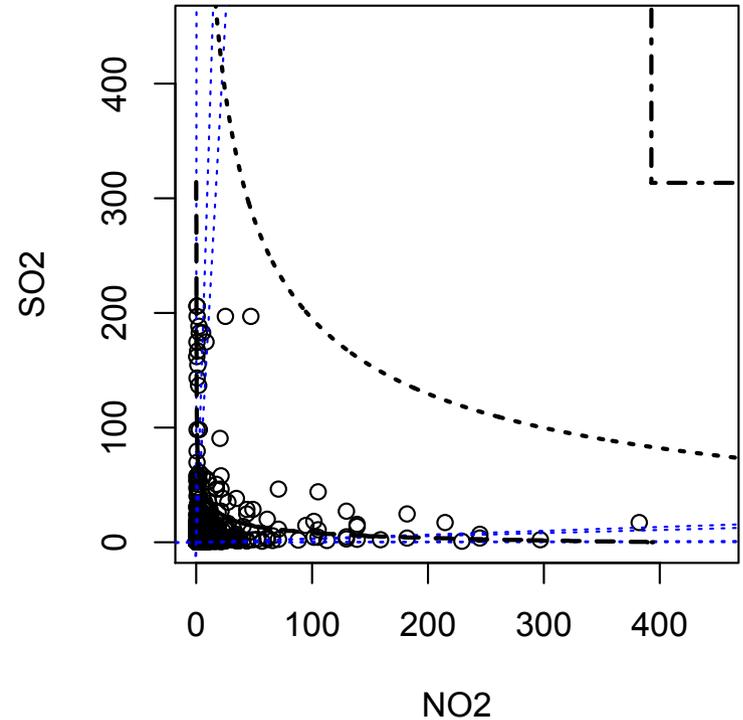
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Motivating Example: Daily Air Pollution, Leeds UK

Daily max pollution at Leeds, UK



Frechet Scale



Data exhibit asymptotic independence (Heffernan and Tawn, 2004).

Outline

- Hidden Regular Variation
- Sum Characterization of HRV
- Estimation via MCEM
- Application: air pollution data

When Multivariate Regular Variation Fails

Multivariate Regular Variation:

$$t\mathbb{P} \left[\frac{R}{b(t)} > r, \mathbf{W} \in B \right] \xrightarrow{v} r^{-\alpha} H(B).$$

In some cases, the angular measure H degenerates on some regions of \mathcal{N} , masking sub-asymptotic dependence features.

Example: asymptotic independence in $d = 2$:

$$\lim_{z \rightarrow z_+} \mathbb{P}(Z_1 > z | Z_2 > z) = 0.$$

- H consists of point masses at $\{0\}$ and $\{1\}$ (using $\|\cdot\|_1$)
- e.g. bivariate Gaussian with correlation $\rho < 1$

Normalization by $b(t)$ kills off sub-asymptotic dependence structure.

Hidden Regular Variation

(Resnick, 2002)

A regular varying random vector \mathbf{Z} exhibits hidden regular variation on a subcone $\mathfrak{C}_0 \subset \mathfrak{C}$ if $\nu(\mathfrak{C}_0) = 0$ and there exists $\{b_0(t)\}$, $b_0(t) \rightarrow \infty$ with $b_0(t)/b(t) \rightarrow 0$ s.t.

$$t\mathbb{P} \left[\frac{\mathbf{Z}}{b_0(t)} \in \cdot \right] \xrightarrow{v} \nu_0(\cdot)$$

as $t \rightarrow \infty$ in $M_+(\mathfrak{C}_0)$.

- Scaling: $\nu_0(tA) = t^{-\alpha_0} \nu_0(A)$ for measurable $A \in \mathfrak{C}_0$, $\alpha_0 \geq \alpha$
- ν_0 is Radon but *not necessarily finite*.

Equivalently,

$$t\mathbb{P} \left[\frac{R}{b_0(t)} > r, \mathbf{W} \in B \right] \xrightarrow{v} r^{-\alpha_0} H_0(B)$$

for B a Borel set of $\mathcal{N}_0 = \mathfrak{C}_0 \cap \mathcal{N}$ (e.g. $\mathcal{N}_0 = (0, 1)$).

H_0 is called the *hidden angular measure*.

Example: bivariate Gaussian

Consider \mathbf{Z} with Fréchet margins and Gaussian dependence, $\rho \in [0, 1)$. Recall ν places mass only on the axes of \mathcal{C} .

Define $\eta = (1 + \rho)/2$, the *coefficient of tail dependence* (Ledford and Tawn, 1997).

- \mathbf{Z} exhibits hidden regular variation of order $\alpha_0 = 1/\eta$
- The density of the hidden measure ν_0 can be written

$$\nu_0(dr \times dw) = \frac{1}{\eta} r^{-(1+1/\eta)} dr \times \underbrace{\frac{1}{4\eta} \{w(1-w)\}^{-1/2\eta-1} dw}_{H_0(dw)}$$

H_0 is infinite on $(0, 1)$.

Tail Equivalence

(Maulik and Resnick, 2004)

Two random vectors \mathbf{X} and \mathbf{Y} are *tail equivalent* on the cone \mathfrak{C}^* if

$$t\mathbb{P} \left[\frac{\mathbf{X}}{b^*(t)} \in \cdot \right] \xrightarrow{v} \nu(\cdot) \quad \text{and} \quad t\mathbb{P} \left[\frac{\mathbf{Y}}{b^*(t)} \in \cdot \right] \xrightarrow{v} c\nu(\cdot)$$

as $t \rightarrow \infty$ in $M_+(\mathfrak{C}^*)$ for $c > 0$.

‘Extremes of \mathbf{X} and \mathbf{Y} samples taken in \mathfrak{C}^* will have the same asymptotic properties.’

Mixture Characterization of HRV

(Maulik and Resnick, 2004)

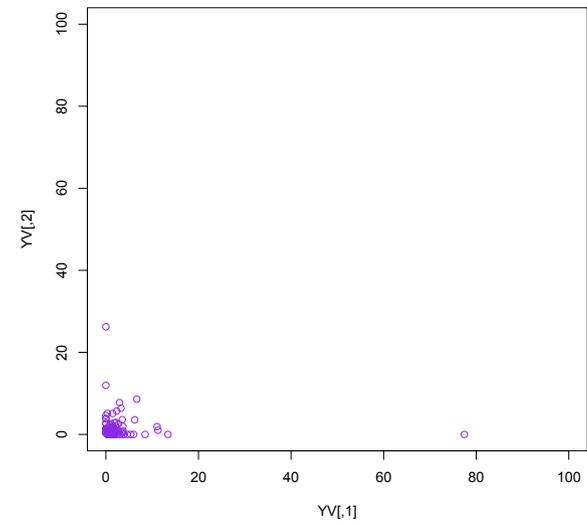
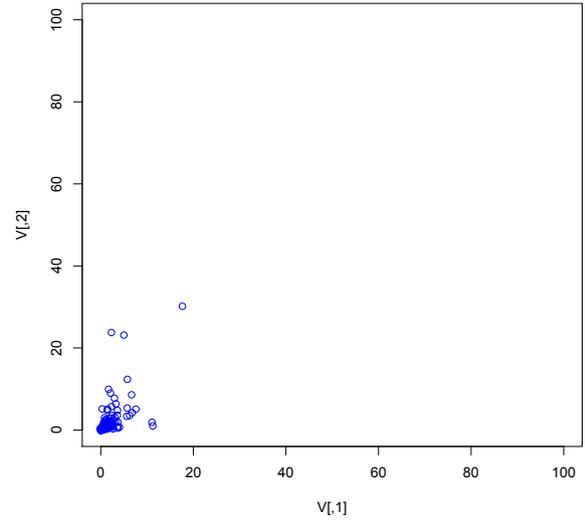
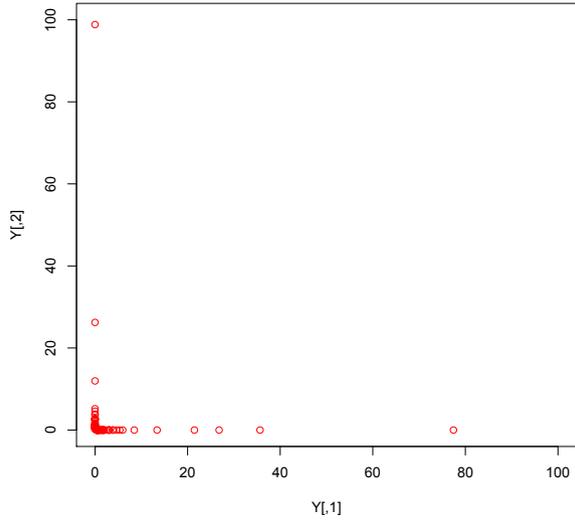
Suppose \mathbf{Z} is regular varying on \mathfrak{E} with hidden regular variation on \mathfrak{E}_0 :

$$t\mathbb{P} \left[\frac{\mathbf{Z}}{b(t)} \in \cdot \right] \xrightarrow{v} \nu(\cdot) \quad \text{in } M_+(\mathfrak{E}) \quad \text{and}$$
$$t\mathbb{P} \left[\frac{\mathbf{Z}}{b_0(t)} \in \cdot \right] \xrightarrow{v} \nu_0(\cdot) \quad \text{in } M_+(\mathfrak{E}_0)$$

with $\nu(\mathfrak{E}_0) = 0$ and $b_0(t)/b(t) \rightarrow 0$ as $t \rightarrow \infty$.

- Let \mathbf{Y} be $RV(\alpha)$ with support only on $\mathfrak{E} \setminus \mathfrak{E}_0$.
- Let $\mathbf{V} = R_0\theta_0$, $R_0 \sim F_{R_0}(t) = 1/b^\leftarrow(t)$ and $\theta_0 \sim H_0$, finite.
- Then \mathbf{Z} is tail equivalent to a mixture of \mathbf{Y} and \mathbf{V} on both \mathfrak{E} and \mathfrak{E}_0 .

Works because \mathbf{Y} 's support doesn't mess with the HRV.



Construction of $\mathbf{Y} + \mathbf{V}$

Define $\mathbf{Y} = R\mathbf{W}$, with $\mathbb{P}(R > r) \sim 1/b^{\leftarrow}(r)$ and \mathbf{W} drawn from limiting angular measure H . Notice that \mathbf{Y} has support only on $\mathfrak{E} \setminus \mathfrak{E}_0$.

Let $\mathbf{V} \in [0, \infty)^d$ be regular varying on \mathfrak{E}_0 with limit measure ν_0 :

$$t\mathbb{P} \left[\frac{\mathbf{V}}{b_0(t)} \in \cdot \right] \xrightarrow{v} \nu_0(\cdot) \quad \text{in } M_+(\mathfrak{E}_0).$$

Further assume that on \mathfrak{E} ,

$$\mathbb{P}(\|\mathbf{V}\| > r) \sim cr^{-\alpha^*}$$

as $r \rightarrow \infty$, with $c > 0$ and

$$\alpha^* > \alpha \vee (\alpha_0 - \alpha).$$

Assume R , \mathbf{W} , \mathbf{V} are independent.

Tail Equivalence Result

Then

$$t\mathbb{P} \left[\frac{\mathbf{Y} + \mathbf{V}}{b(t)} \in \cdot \right] \xrightarrow{v} \nu(\cdot) \text{ in } M_+(\mathfrak{C})$$

(Jessen and Mikosch, 2006).

Furthermore, tail equivalence (Maulik and Resnick, 2004) also holds on \mathfrak{C}_0 :

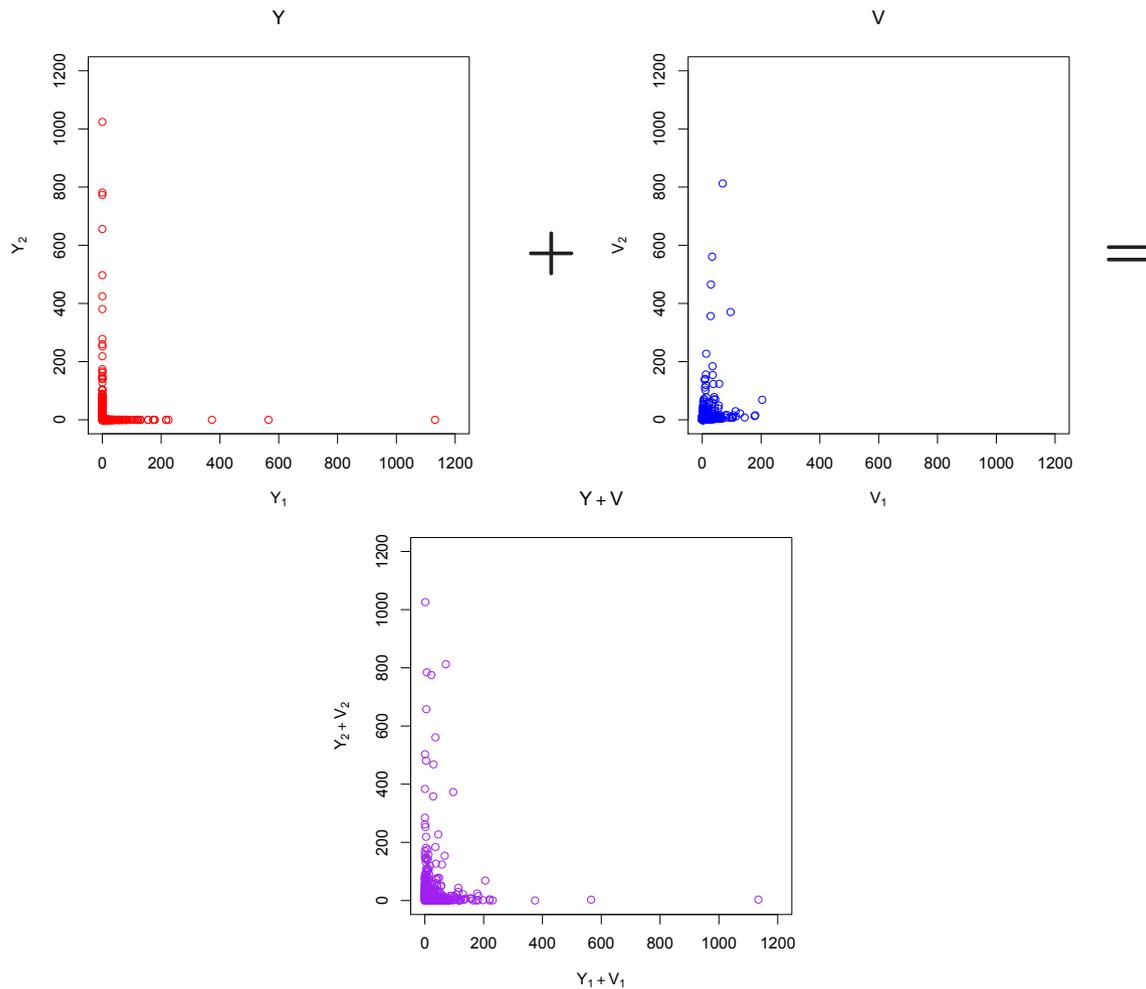
Theorem. *With \mathbf{Y} and \mathbf{V} as defined above,*

$$t\mathbb{P} \left[\frac{\mathbf{Y} + \mathbf{V}}{b_0(t)} \in \cdot \right] \xrightarrow{v} \nu_0(\cdot) \text{ in } M_+(\mathfrak{C}_0).$$

View \mathbf{Z} as a sum of ‘first-order’ \mathbf{Y} and ‘second-order’ \mathbf{V} .

The sum $\mathbf{Y} + \mathbf{V}$ is *tail equivalent* to \mathbf{Z} on *both* \mathfrak{C} and \mathfrak{C}_0 .

Simulation when ν_0 is finite.



No point falls exactly on an axis.

Infinite Measure Example: Bivariate Gaussian

\mathbf{Z} has Fréchet margins and Gaussian dependence ($\rho < 1$).
Recall: H_0 is *infinite* on $\mathcal{N}_0 = (0, 1)$.

Poses difficulty near the axes of \mathfrak{C} .

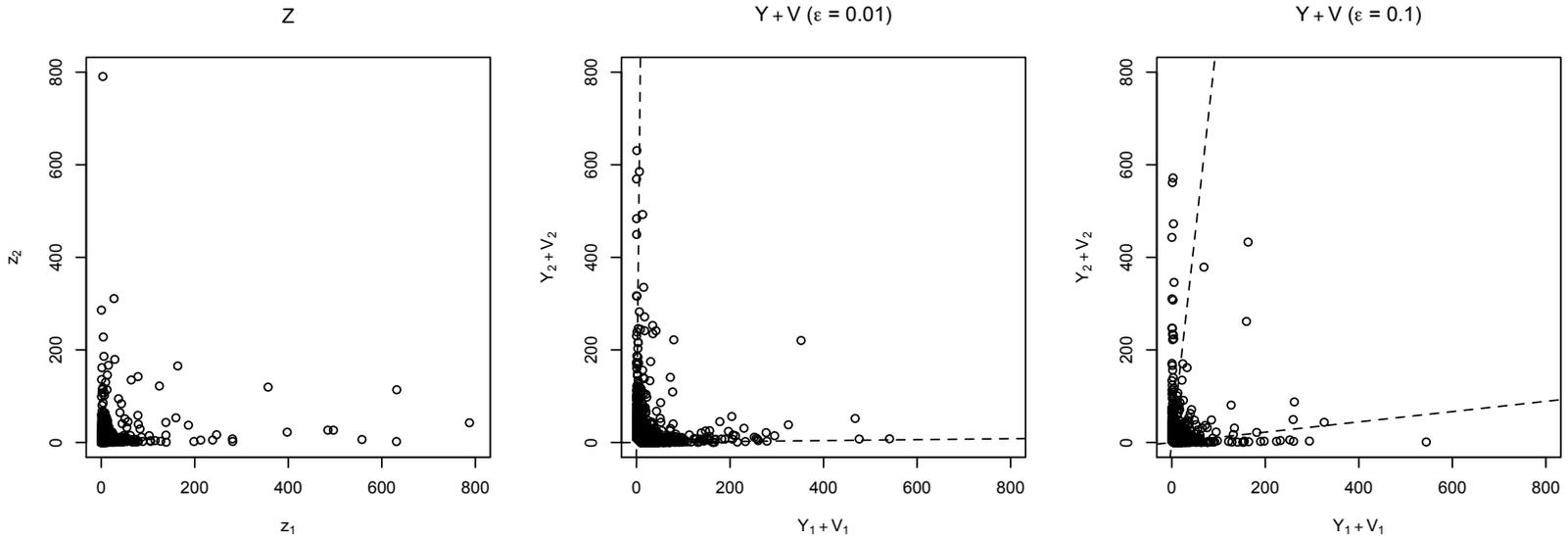
Proposed construction of \mathbf{V} :

- Restrict to $\mathfrak{C}_0^\epsilon = \mathfrak{C}_0 \cap \mathcal{N}_0^\epsilon$, where $\mathcal{N}_0^\epsilon = [\epsilon, 1 - \epsilon]$ for $\epsilon \in (0, 1/2)$.
- Simulate W_0 from probability density $H_0(dw)/H_0(\mathcal{N}_0^\epsilon)$
- Let R_0 follow a Pareto distribution with $\alpha = 1/\eta$
- $\mathbf{V} = [R_0 W_0, R_0(1 - W_0)]^T$

$\mathbf{Y} + \mathbf{V}$ is tail equivalent to \mathbf{Z} on \mathfrak{C} and \mathfrak{C}_0^ϵ .

Sum representation of bivariate Gaussian

Example with $\rho = 0.5$ ($n = 2500$):



For any set completely contained in \mathcal{C}_0^ϵ we achieve the correct limit measure ν_0 .

Choice of ϵ involves a trade-off between:

- Size of the subcone on which tail equivalence holds
- Threshold at which $\mathbf{Y} + \mathbf{V}$ is a useful approximation
- Biases due to choice of ϵ calculated.

Inference via the EM Algorithm

Observe realizations from \mathbf{Z} , tail equivalent to $\mathbf{Y} + \mathbf{V}$. Assume parametric forms and perform ML inference via EM.

If we assume $\mathbf{Z} = \mathbf{Y} + \mathbf{V}$,

$$\begin{aligned}\log f(\mathbf{z}; \boldsymbol{\theta}) &= \int \log f(\mathbf{z}, \mathbf{y}, \mathbf{v}; \boldsymbol{\theta}) f(\mathbf{y}, \mathbf{v} | \mathbf{z}; \boldsymbol{\theta}^{(k)}) d\mathbf{y} d\mathbf{v} \\ &\quad - \int \log f(\mathbf{y}, \mathbf{v} | \mathbf{z}; \boldsymbol{\theta}) f(\mathbf{y}, \mathbf{v} | \mathbf{z}; \boldsymbol{\theta}^{(k)}) d\mathbf{y} d\mathbf{v} \\ &:= Q(\boldsymbol{\theta} | \boldsymbol{\theta}^{(k)}) - H(\boldsymbol{\theta} | \boldsymbol{\theta}^{(k)}).\end{aligned}$$

Here: \mathbf{Z} and $\mathbf{Y} + \mathbf{V}$ are only *tail equivalent*; $\boldsymbol{\theta}$ governs tail behavior of \mathbf{Y} and \mathbf{V} . Requires a modification of the EM setup.

EM for Extremes

Consider distributions with densities $g_{\mathbf{Y}}(\mathbf{y}; \boldsymbol{\theta})$ and $g_{\mathbf{V}}(\mathbf{v}; \boldsymbol{\theta})$ which are tail equivalent to the true distributions; i.e.,

$$\begin{aligned} g_{\mathbf{Y}}(\mathbf{y}; \boldsymbol{\theta}) &\cong f_{\mathbf{Y}}(\mathbf{y}; \boldsymbol{\theta}) & \text{for } \|\mathbf{y}\| > r_{\mathbf{Y}}^* \\ g_{\mathbf{V}}(\mathbf{v}; \boldsymbol{\theta}) &\cong f_{\mathbf{V}}(\mathbf{v}; \boldsymbol{\theta}) & \text{for } \|\mathbf{v}\| > r_{\mathbf{V}}^*, \end{aligned}$$

Complete likelihood is based on limiting Poisson point processes for \mathbf{Y} and \mathbf{V} .

- E step: expectation is taken with respect to $g(\mathbf{y}, \mathbf{v} | \mathbf{z}; \boldsymbol{\theta})$.
- M step: maximization is taken over only ‘large’ \mathbf{y} and \mathbf{v} .

We show

$$H(\boldsymbol{\theta}^{(k)} | \boldsymbol{\theta}^{(k)}) - H(\boldsymbol{\theta} | \boldsymbol{\theta}^{(k)}) \geq 0$$

using Jensen’s inequality.

MCEM

Natural framework for MCEM.

At the E step of the $(k + 1)^{th}$ iteration, simulate from

$$g_Y(\mathbf{y}; \boldsymbol{\theta}^{(k)})g_V(\mathbf{z} - \mathbf{y}; \boldsymbol{\theta}^{(k)}) \propto g(\mathbf{y}, \mathbf{v}|\mathbf{z}; \boldsymbol{\theta}^{(k)})$$

for all \mathbf{z} and use the simulated realizations to compute

$$\hat{Q}_m(\boldsymbol{\theta}|\boldsymbol{\theta}^{(k)}) = \frac{1}{m} \sum_{j=1}^m \ell(\boldsymbol{\theta}; \mathbf{z}, \mathbf{y}_j, \mathbf{v}_j).$$

employing Poisson point process likelihoods for *large* realizations of \mathbf{Y} and \mathbf{V} .

Key idea: likelihood only depends on $\boldsymbol{\theta}$ for 'large' \mathbf{y} and \mathbf{v} !

Uncertainty estimates obtained via Louis' method.

Example w/ Infinite Hidden Measure

Simulate $n = 10000$ realizations from a bivariate Gaussian distribution with correlation ρ , transform marginals to unit Fréchet.

Tail equivalent on \mathfrak{C} and \mathfrak{C}_0^ϵ to $\mathbf{Y} + \mathbf{V}$, where \mathbf{V} has angular measure

$$H_0(dw) = \frac{1}{4\eta} \{w(1-w)\}^{-1/2\eta-1} dw.$$

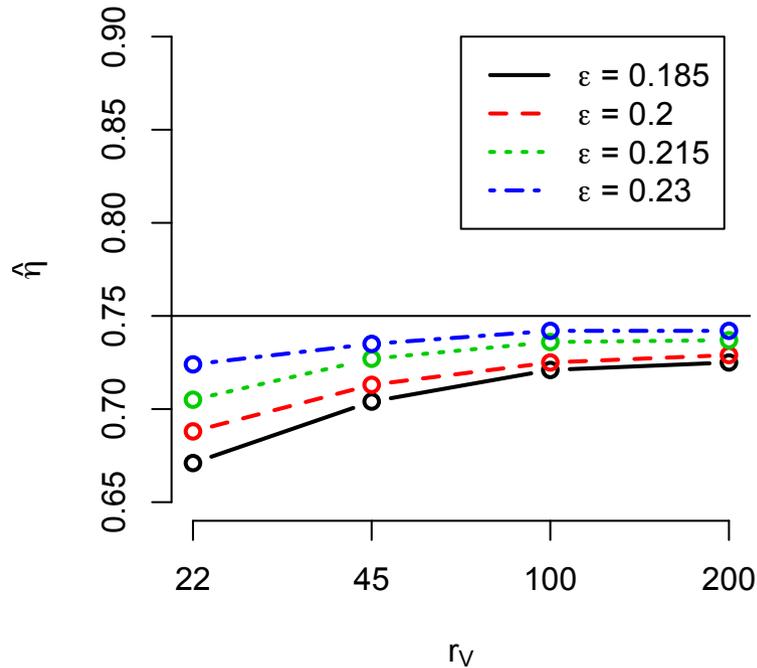
Aim: estimate $\eta = (1 + \rho)/2$ from the ϵ -restricted model.

- Must select both ϵ and $r_{\mathbf{V}}^*$
- Trade-off in finite sample estimation problems

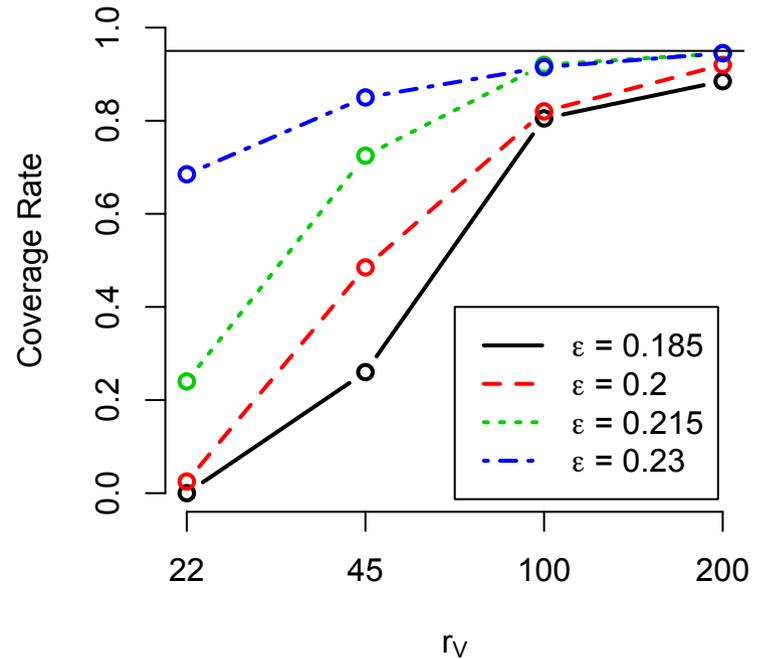
Infinite Hidden Measure Results

Shown for $\eta = 0.75$ ($\rho = 0.5$)

Mean estimates of η

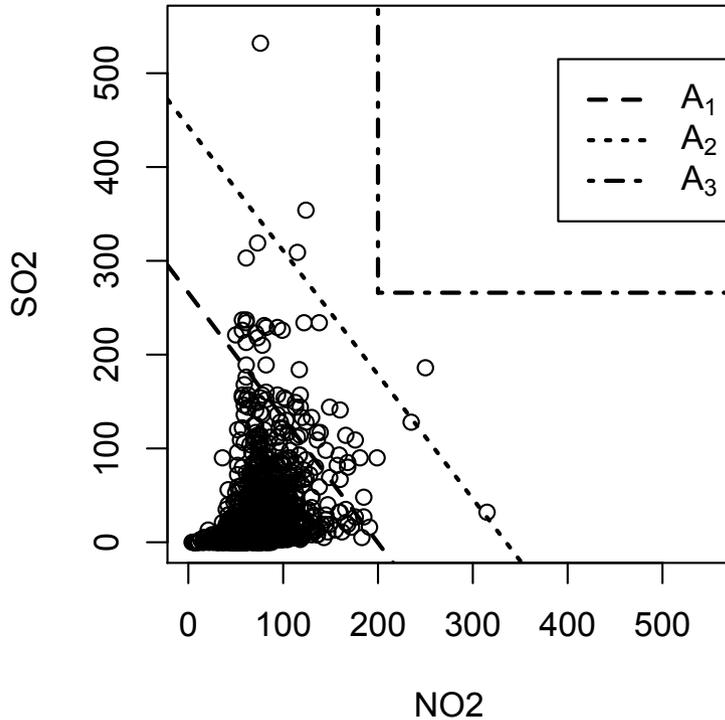


Coverage rates of 95% CI

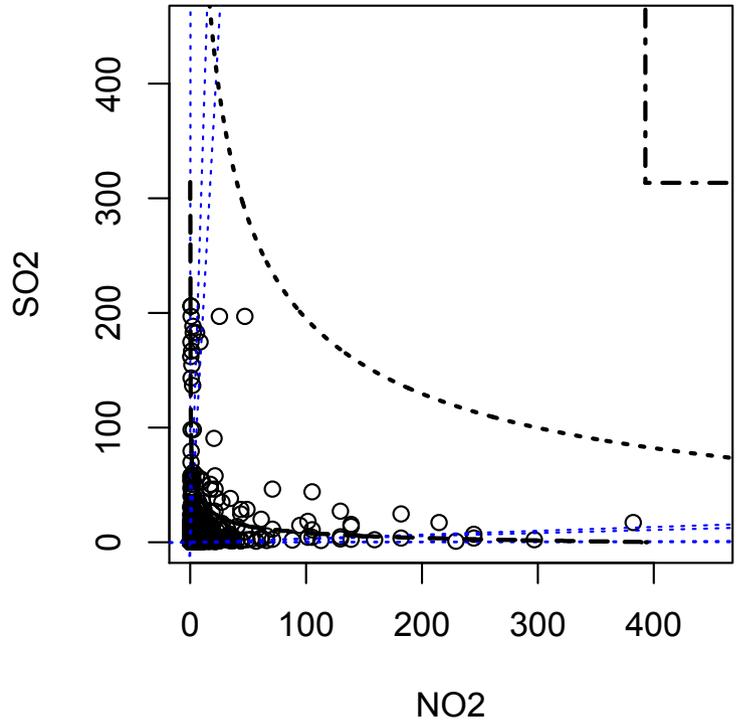


Air Pollution Data

Daily max pollution at Leeds, UK



Frechet Scale



- Strong evidence for asymptotic independence
- Aim: estimate risk set probabilities

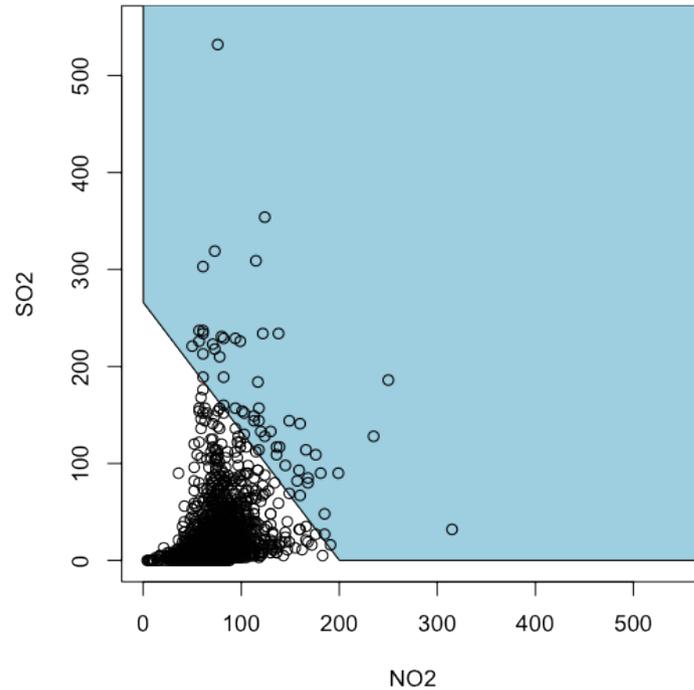
Competing Approaches

Examine three modeling approaches:

1. Assume asymptotic dependence; i.e. that $\nu(\cdot)$ places mass on the entire cone \mathcal{C} . Fit a bivariate logistic angular dependence model to largest 10% of observations (in terms of L_1 norm). Estimate $\hat{\beta} = 0.713$.
2. Assume asymptotic independence and ignore any possible hidden regular variation.
3. Assume asymptotic independence and hidden regular variation. Fit the ϵ -restricted infinite hidden measure model via MCEM. Select $r_V^* = 7.5$ and $\epsilon = 0.3$. Estimate $\hat{\eta} = 0.748$.

Results - risk set estimates

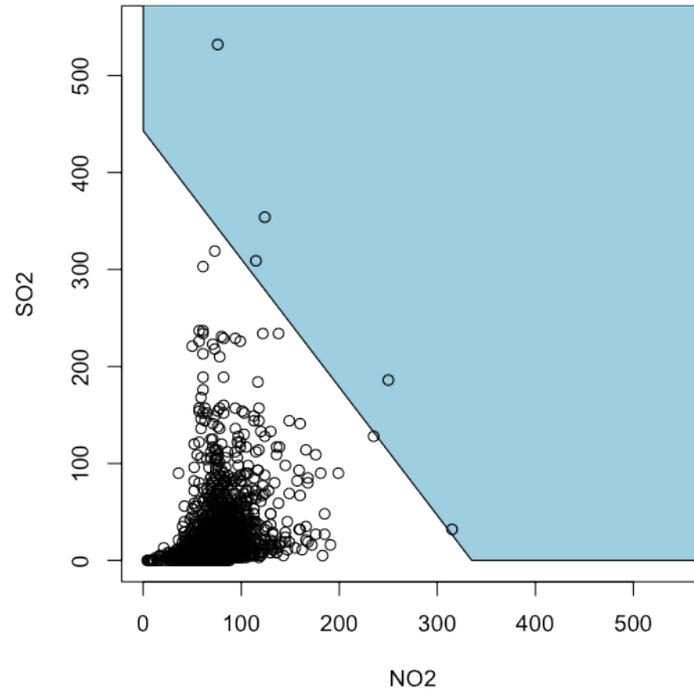
Daily max pollution at Leeds, UK



Model	$\hat{\mathbb{P}}(\mathbf{Z} \in A_1)$	Expected #	p -val
1 (asy. dep.)	0.0297	59.04	0.480
2 (asy. indep.)	0.0120	23.86	8.17×10^{-5}
3 (Y + V)	0.0261	51.89	0.210
Empirical	0.0292	58	—

Results - risk set estimates

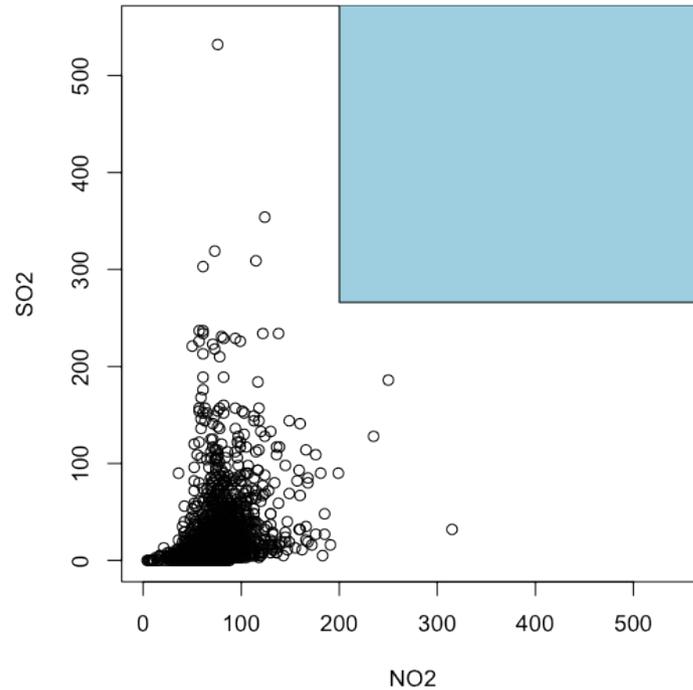
Daily max pollution at Leeds, UK



Model	$\hat{\mathbb{P}}(\mathbf{Z} \in A_2)$	Expected #	p -val
1 (asy. dep.)	0.0044	8.74	0.132
2 (asy. indep.)	0.0002	0.40	0.009
3 ($Y + V$)	0.0018	3.58	0.274
Empirical	0.0025	5	—

Results - risk set estimates

Daily max pollution at Leeds, UK



Model	$\hat{\mathbb{P}}(\mathbf{Z} \in A_3)$	Expected #	p -val
1 (asy. dep.)	0.0010	1.99	0.130
2 (asy. indep.)	0	0	1
3 ($\mathbf{Y} + \mathbf{V}$)	0.0002	0.40	0.704
Empirical	0	0	—

Summary

This work introduces a sum representation for regular varying random vectors possessing hidden regular variation.

- Useful representation for finite samples
- Asymptotically justified by tail equivalence result
- Difficulty arises when H_0 is infinite - restrict to a compact cone to simulate \mathbf{V}
- Likelihood estimation via modified MCEM algorithm
- Captures tail dependence in the presence of asymptotic independence
- Improved estimation of tail risk set probabilities

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