Alberto Santini

# Topological groupoids 

## Kandidatproject

Institut for Matematiske Fag,
Københavns Universitet.
Lektor: Jesper Michael Møller

## Contents

1 Basic concepts ..... 2
1.1 Introduction to categories ..... 2
1.2 Groupoids and the fundamental groupoid ..... 8
1.3 Functors ..... 13
1.4 Pushouts ..... 18
1.5 Further properties of the fundamental groupoid ..... 22
1.6 The fundamental group of the circle ..... 27
1.7 Fibrations of groupoids and cofibrations of spaces ..... 29
2 Products and quotients of groupoids ..... 34
2.1 Universal morphisms and universal groupoids ..... 34
2.2 Free groupoids and free product of groupoids ..... 36
2.3 Quotient groupoids ..... 40
2.4 Adjunction spaces ..... 41
2.5 Van Kampen theorem for the fundamental groupoid ..... 43
Index ..... 47
Bibliography ..... 49

## BASIC CONCEPTS

### 1.1 Introduction to categories

There are basically two ways of approaching groupoids. The first one is algebraically, considering them as a particular generalization of the algebraic structure of group. The second one, that is the one we'll use and need to prove our results is the category theoretical approach. To do this, we'll introduce some basic aspects of category theory, with in mind the fact that we'll always use it as tool for our topological aim. Categories have been introduced by Saunders Mac Lane ([3]) and Samuel Eilenberg as a way to generalize particular dual properties of groups and lattices, but then they have proven useful as a generalization of almost all algebraic structures mathematicians usually deal with. Their basic constituents are objects and morphisms (sometimes called arrows) that satisfy certain axioms, as explained in what follows.

Definition 1.1.1. A category is a quadruple $\mathbf{A}=(\operatorname{Obj}(\mathbf{A}), \mathrm{Hom}, \mathrm{Id}, \circ)$ where

- $\operatorname{Obj}(\mathbf{A})$ is a class, whose members are called the objects of $\mathbf{A}$.
- For each $A, B \in \operatorname{Obj}(\mathbf{A}), \operatorname{Hom}_{\mathbf{A}}(A, B)$ is a set whose elements are called morphisms and are denoted as $A \xrightarrow{f} B$; we also call $A$ the domain and $B$ the codomain of $f$.
- For each $A \in \operatorname{Obj}(\mathbf{A}), \operatorname{Id}_{\mathbf{A}, A}$ is a morphism $A \xrightarrow{\mathrm{Id}_{\mathbf{A}, A}} A$, called the identity on $A$.
- For each $A, B, C, \in \operatorname{Obj}(\mathbf{A})$ and each $A \xrightarrow{f} B, B \xrightarrow{g} C, g \circ f$ is a morphism $A \xrightarrow{g \circ f} C ; \circ$ is called a composition law.
such that the following holds:
C1 The compositiono is associative: given $A \xrightarrow{f} B, B \xrightarrow{g} C, C \xrightarrow{h} D$ we have $(f \circ g) \circ h=f \circ(g \circ h)$.
$\mathbf{C} 2$ The identities $\operatorname{Id}_{\mathbf{A}, A}$ actually act as identities for the composition: given $A \xrightarrow{f} B$ we have that $f \circ \operatorname{Id}_{\mathbf{A}, A}=f$ and $\operatorname{Id}_{\mathbf{A}, B} \circ f=f$.

C3 The various sets $\operatorname{Hom}_{\mathbf{A}}(A, B)$ are pairwise disjoint.
We will sometimes refer to

$$
\begin{align*}
& \operatorname{Hom}_{\mathbf{A}}:=\bigsqcup_{A, B \in \operatorname{Obj}(\mathbf{A})} \operatorname{Hom}_{\mathbf{A}}(A, B)  \tag{1.1.1}\\
& \operatorname{Hom}_{\mathbf{A}}(A,-):=\bigsqcup_{B \in \operatorname{Obj}(\mathbf{A})}^{\bigsqcup} \operatorname{Hom}_{\mathbf{A}}(A, B)  \tag{1.1.2}\\
& \operatorname{Hom}_{\mathbf{A}}(-, B):=\bigsqcup_{A \in \operatorname{Obj}(\mathbf{A})}^{\bigsqcup} \operatorname{Hom}_{\mathbf{A}}(A, B) \tag{1.1.3}
\end{align*}
$$

Example 1.1.2. Examples of categories are:

- Set where the objects are the sets and the morphisms are functions between them.
- Pos where the objects are partially ordered sets and the morphisms are the isomorphisms between posets (i.e. order-preserving maps).
- Lin where the objects are finite-dimensional $K$-vector spaces and the morphisms are the linear maps between them.
- Grp where the objects are groups and the morphisms are group homomorphisms.
- Every monoid $M$ is also a category with just an object, $M$ itself and whose morphisms are the elements of $M$ (so that the identity is the identity of $M$ and the composition is just the multiplication on $M$ ).
- Top where the objects are topological spaces and the morphisms are continuous functions between them.
- Given a topological space $X$, we define the category $\mathbf{P} X$; the objects are the points of $X$ and the morphisms are the paths between them (a path from $x \in X$ to $y \in X$ is a continuous function $p_{x, y}:[0,1] \rightarrow X$ such that $p_{x, y}(0)=x$ and $\left.p_{x, y}(1)=y\right)$. The identity for $x \in X$ is the null-path - i.e. the constant function $p_{x, x}(t)=x \forall t \in[0,1]$ - and the composition is the concatenation of paths.

Definition 1.1.3. Given two categories $\mathbf{A}$ and $\mathbf{B}$ we say that $\mathbf{B}$ is a subcategory of A if

- $\operatorname{Obj}(\mathbf{B}) \subseteq \operatorname{Obj}(\mathbf{A})$.
- Given two objects $A, B \in \operatorname{Obj}(\mathbf{B})$ we have that $\operatorname{Hom}_{\mathbf{B}}(A, B) \subseteq \operatorname{Hom}_{\mathbf{A}}(A, B)$.
- Composition in $\mathbf{B}$ is the same as the one in $\mathbf{A}$.
- For each $A \in \operatorname{Obj}(\mathbf{B})$ we have $\operatorname{Id}_{\mathbf{B}, A}=\operatorname{Id}_{\mathbf{A}, A}$.
$\mathbf{B}$ is said to be wide if it has exactly the same objects as $\mathbf{A}$, while it is said to be full if each couple of objects of $\mathbf{B}$ has the same morphisms both in $\mathbf{A}$ and $\mathbf{B}$.

Definition 1.1.4. Given two morphisms $A \xrightarrow{f} B$ and $B \xrightarrow{g} A$, we say that they are respectively a co-retraction and a retraction if $g \circ f=\operatorname{Id}_{\mathbf{A}, A}$. Sometimes we say that $g$ is a left-inverse of $f$ and $f$ is a right-inverse of $g$. The following theorem will show that, fixed a morphism that has both a left and right inverse, it is legitimate to simply refer to its inverse - without specifying if left or right. We will call such a morphism invertible or an isomorphism.

Theorem 1.1.5. Given $A \xrightarrow{f} B$ and $B \xrightarrow{g} A, B \xrightarrow{h} A$, if $g \circ f=\operatorname{Id}_{\mathbf{A}, B}$ and $f \circ h=\operatorname{Id}_{\mathbf{A}, A}$, then $g=h$.

Proof.

$$
\begin{equation*}
g=g \circ \operatorname{Id}_{\mathbf{A}, A}=g \circ(f \circ h)=(g \circ f) \circ h=\operatorname{Id}_{\mathbf{A}, B} \circ h=h \tag{1.1.5}
\end{equation*}
$$

Definition 1.1.6. Two objects $A, B \in \operatorname{Obj}(\mathbf{A})$ are called isomorphic if there exists an isomorphism $A \xrightarrow{f} B$. It's trivial to prove that the relation "is isomorphic to" is an equivalence relation on $\operatorname{Obj}(\mathbf{A})$, if this is a set.

Exercise 1.1.7. An object $O_{i} \in \operatorname{Obj}(\mathbf{C})$ is said to be initial if $\left|\operatorname{Hom}_{\mathbf{C}}\left(O_{i}, A\right)\right|=1$ for all $A \in \operatorname{Obj}(\mathbf{C})$. Analogously $O_{f} \in \operatorname{Obj}(\mathbf{C})$ is called final if $\left|\operatorname{Hom}_{\mathbf{C}}\left(A, O_{f}\right)\right|=1$ for all $A \in \operatorname{Obj}(\mathbf{C})$. An object that is both initial and final is called a zero object.

- Prove that all initial objects are isomorphic - as are all final objects.
- Prove that Set and Top have initial and final objects but no zero object.
- Prove that Grp has a zero object.

Proof.

- Let $A, B \in \operatorname{Obj}(\mathbf{C})$ be two initial objects. By hypothesis there are unique morphisms $A \xrightarrow{f} B$ and $B \xrightarrow{A}$, so there is a morphism $A \xrightarrow{g \circ f} A$. But since $A$ is initial $\operatorname{Hom}_{\mathbf{C}}(A, A)$ has only one element, so we must have that $g \circ f=\operatorname{Id}_{\mathbf{C}, A}$ and analogously $f \circ g=\operatorname{Id}_{\mathbf{C}, B}$, so $A$ and $B$ are isomorphic. An entirely similar reasoning may be applied to final objects.
- Since functions can have empty domains, but can't have empty codomains it's clear that the only initial object in Set is $\emptyset$. On the other hand, the only object that allow only one map to be constructed such that it has the object as codomain, must have only one element and so the final objects are the singletons. Hence it's clear then there is no zero object in Set. Reasoning in the exact same way one can find that the empty space is the only initial object of Top and that one-point space are its only final objects.
- Consider any group $G=\left\{e_{G}\right\}$. By the very definition, there is just one homomorphism from $G$ to any other group $H$ (and it is $e_{G} \mapsto e_{H}$ ) and one homomorphism from $H$ to $G$ (and it is $h \mapsto e_{G}$ for all $h \in H$ ).

Exercise 1.1.8. A morphism $A \xrightarrow{f} B$ of $\mathbf{C}$ is called a monomorphism if

$$
\begin{equation*}
\forall C \in \operatorname{Obj}(\mathbf{C}) \forall g, h \in \operatorname{Hom}_{\mathbf{C}}(C, A) f \circ g=f \circ h \Rightarrow g=h \tag{1.1.6}
\end{equation*}
$$

Analogously it is called an epimorphism if

$$
\begin{equation*}
\forall C \in \operatorname{Obj}(\mathbf{C}) \forall g, h \in \operatorname{Hom}_{\mathbf{C}}(B, C) g \circ f=h \circ f \Rightarrow g=h \tag{1.1.7}
\end{equation*}
$$

We write monomorphisms as $A \stackrel{f}{\longrightarrow} B$ and epimorphisms as $A \xrightarrow{f} B$.

- Prove that a morphism of Set is a monomorphism if and only if it is injective.
- Prove that a morphism of Set is an epimorphism if and only if it is surjective.
- Prove that every isomorphism is both a monomorphism and an epimorphism.
- Give an example of a category that has a morphism that is both an epimorphism and a monomorphism, but not an isomorphism.

Proof.

- Given $A \stackrel{f}{\mapsto} B$ and $a, a^{\prime} \in A$ with $a \neq a^{\prime}$, consider a singleton $\{s\} \in \operatorname{Obj}($ Set $)$ and the functions

$$
\begin{equation*}
f_{a}, f_{a^{\prime}}:\{s\} \rightarrow A: f_{a}(x)=a \wedge f_{a^{\prime}}(x)=a^{\prime} \tag{1.1.8}
\end{equation*}
$$

Since $f$ is a monomorphism, we have that $a \neq a^{\prime} \Rightarrow f \circ f_{a} \neq f \circ f_{a^{\prime}}$ and so

$$
\begin{equation*}
f(a)=f\left(f_{a}(x)\right) \neq f\left(f_{a^{\prime}}(x)\right)=f\left(a^{\prime}\right) \tag{1.1.9}
\end{equation*}
$$

On the other hand, if $f$ is injective, given $g, h: C \rightarrow A$ with $g \neq h$, let $c \in C$ be a point such that $g(c) \neq h(c)$. Then by injectivity $f(g(c)) \neq f(h(c))$ and so $f \circ g \neq f \circ h$.

- Given $A \xrightarrow{f} B$, consider a set with two elements $\{s, t\} \in \operatorname{Obj}($ Set $)$ and the functions

$$
\begin{align*}
& B \xrightarrow{g, h}\{s, t\}  \tag{1.1.10}\\
& g(x)=s \quad \forall x \in B  \tag{1.1.11}\\
& h(x)= \begin{cases}s & \text { if } x \in f(A) \\
t & \text { if } x \notin f(A)\end{cases} \tag{1.1.12}
\end{align*}
$$

Now notice that $\forall a \in A$ we have that $g(f(a))=s$ and $h(f(a))=s$, so $g \circ f=h \circ f$ and since $f$ is an epimorphism this implies that $g=h$, that is to say that $\forall x \in B \quad x \in f(A)$ and so $f$ is injective. On the other hand, given the injection $A \xrightarrow{f} B$, consider $C \in \mathrm{Obj} \mathbf{C}$ and the morphisms $B \xrightarrow{g, h} C$ such that $g \circ f=h \circ f$. By surjectivity, each $b \in B$ can be written as $f(a)$ for some $a \in A$. So we have that

$$
\begin{equation*}
g(b)=g(f(a))=(g \circ f)(a)=(h \circ f)(a)=h(f(a))=h(b) \quad \forall b \in B \tag{1.1.13}
\end{equation*}
$$

ans so $g=h$, that is to say $f$ is an epimorphism.

- Given an isomorphism $A \xrightarrow{f} B$, let $B \xrightarrow{g} A$ be its inverse. Given $C \in \operatorname{Obj}(\mathbf{C})$ and two morphisms $C \xrightarrow{h, j} A$ such that $f \circ h=f \circ j$ we have that

$$
\begin{equation*}
h=(g \circ f) \circ h=g \circ(f \circ h)=g \circ(f \circ j)=(g \circ f) \circ j=j \tag{1.1.14}
\end{equation*}
$$

and so $f$ is a monomorphism. In a totally analogous way one proves that it is also an epimorphism.

- Here the inclusions of smaller objects into bigger objects (in sufficiently good categories) seem to be good candidates of such morphisms, since they are injective but not surjective. The problem arises when one wants to prove that they are epimorphism, since two functions that are equal when restricted to smaller objects are not equal in general. This last observation, however is a precious hint, since there is a famous case in which equality on restriction implies equality. Consider the category Top of topological spaces and take $\mathbb{R}, \mathbb{Q} \in \operatorname{Obj}(\mathbf{T o p})$ where those spaces are taken with the usual euclidean topology on $\mathbb{R}$ and the induced topology on $\mathbb{Q}$. Notice that, by the very definition, the isomorphisms of Top are the homeomorphic maps between spaces. So it's clear that the canonical inclusion $i: \mathbb{Q} \rightarrow \mathbb{R}$ is not an isomorphism. However, let's show that it is both a monomorphism and an epimorphism. Given a space $X \in \operatorname{Obj}(\mathbf{T o p})$ and two morphisms (continuous maps) $f, g: X \rightarrow \mathbb{Q}$ such that $i \circ f=i \circ g$ we have that by injectivity

$$
\begin{equation*}
(i \circ f)(x)=(i \circ g)(x) \Rightarrow f(x)=g(x) \quad \forall x \in X \tag{1.1.15}
\end{equation*}
$$

and so $i$ is a monomorphism. On the other hand, given the continuous maps $f, g: \mathbb{R} \rightarrow X$ such that $f \circ i=g \circ i$, we have that

$$
\begin{equation*}
\forall q \in \mathbb{Q}(f \circ i)(q)=(g \circ i)(q) \Rightarrow f(i(q))=g(i(q)) \Rightarrow f(q)=g(q) \tag{1.1.16}
\end{equation*}
$$

so $f, g$ have the same values on the rationals. But $\mathbb{Q}$ is a dense subset of $\mathbb{R}$ and $f, g$ are continuous; it's a very well known fact that $f \upharpoonright \mathbb{Q}=g \upharpoonright \mathbb{Q} \Rightarrow f=g$ and so $i$ is an epimorphism. In case one doesn't trust common knowledge, it is also easy to prove this result. Given $x \in \mathbb{R}$ consider a sequence $\left\langle x_{n}: n \in \mathbb{N}\right\rangle \subset \mathbb{Q}$ with the Cauchy property and such that $\lim _{n} x_{n}=x$. Since $f\left(x_{n}\right)=g\left(x_{n}\right) \forall n \in \mathbb{N}$ and $f, g$ are continuous, they can be put into the limit and so

$$
\begin{equation*}
f(x)=\lim _{n} f\left(x_{n}\right)=\lim _{n} g\left(x_{n}\right)=g(x) \tag{1.1.17}
\end{equation*}
$$

### 1.2 Groupoids and the fundamental groupoid

In this section, we introduce the main tool we will use to study relevant properties of topological spaces: groupoids and in particular the fundamental groupoid, that can be regarded roughly as the groupoid of the paths of a space.

Definition 1.2.1. We say that a category $\mathbf{A}$ is a groupoid if $\operatorname{Obj}(\mathbf{A})$ is a set and if all its morphisms are isomorphisms. A subgroupoid of $\mathbf{A}$ is a subcategory $\mathbf{B}$ of $\mathbf{A}$ such that $\mathbf{B}$ is itself a groupoid - i.e. for every morphism of $\mathbf{B}$, its inverse is also a morphism of $\mathbf{B}$.

Definition 1.2.2. Consider the space $\mathbf{P} X$ of example 1.1.2. Remember that its morphisms were the paths between two points: given $x, y \in X$ we have that

$$
\begin{equation*}
\operatorname{Hom}_{\mathbf{P} X}(x, y)=\{a:[0,1] \rightarrow X \text { continuous }: a(0)=x \wedge a(1)=y\} \tag{1.2.1}
\end{equation*}
$$

We now introduce an equivalence relation in $\operatorname{Hom}_{\mathbf{P} X}(x, y)$. We will say that two paths $a, b$ are homotopic rel endpoints $x, y$ if there exists an homotopy of paths between
them. Such a homotopy is a continuous function $F:[0,1]^{2} \rightarrow X$ such that

$$
\begin{align*}
& F(0, t)=a(t) \wedge F(1, t)=b(t) \forall t \in[0,1]  \tag{1.2.2}\\
& F(s, 0)=x \wedge F(s, 1)=y \forall s \in[0,1] \tag{1.2.3}
\end{align*}
$$

It is trivial to check that this actually is an equivalence relation; we will denote it by $\sim$. So, intuitively, $a \sim b$ if we can construct a continuous family of paths from $x$ to $y$ such that the first of those paths is just $a$ and the last is $b$.

Exercise 1.2.3. Prove that $\sim$ preserves the operation of concatenation of paths.
Proof. Given $x, y, z \in X$ and $a, b \in \operatorname{Hom}_{\mathbf{P} X}(x, y), c, d \in \operatorname{Hom}_{\mathbf{P} X}(y, z)$ such that $a \sim b$ through homotopy $F$ and $c \sim d$ through homotopy $G$, then we have that $a+c \sim b+d$ and the homotopy is $H:[0,1]^{2} \rightarrow X$ given by

$$
H(s, t)= \begin{cases}F(s, 2 t) & \text { if } t \in\left[0, \frac{1}{2}[ \right.  \tag{1.2.4}\\ G(s, 2 t-1) & \text { if } t \in\left[\frac{1}{2}, 1\right]\end{cases}
$$

Also, if we call $0_{x}$ the constant path at $x, 0_{x}=[0,1] \times\{x\}$, given any path $a$ from $x$ to $y$ we have that $a+(-a) \sim 0_{x}$. In fact, a homotopy between them is $H:[0,1]^{2} \rightarrow X$ given by:

$$
H(s, t)= \begin{cases}a((1-s) 2 t) & \text { if } t \in\left[0, \frac{1}{2}[ \right.  \tag{1.2.5}\\ a(s(2 t-1)) & \text { if } t \in\left[\frac{1}{2}, 1\right]\end{cases}
$$

Definition 1.2.4. We may now define the fundamental groupoid of a space $X$ as a groupoid $\pi X$ with $\operatorname{Obj}(\pi X)=X$ and $\operatorname{Hom}_{\pi X}(x, y)=\operatorname{Hom}_{\mathbf{P}}(x, y) / \sim$. To show that this definition actually makes sense, we'll have to prove the next simple theorem.

Theorem 1.2.5. If we call $[a]$ the equivalence class of $a \in \operatorname{Hom}_{\mathbf{P}}^{X}(x, y)$ in $\operatorname{Hom}_{\pi X}$, we have that

1. $-[a]=[-a]$ for every $x \xrightarrow{a} y$.
2. $[a]+[b]=[a+b]$ where $x \xrightarrow{a} y$ and $y \xrightarrow{b} z$, as proven in exercise 1.2.3.
3. $[a]+\left[0_{y}\right]=\left[0_{x}\right]+[a]=[a]$ for every $x \xrightarrow{a} y$.
4. $[a]+[-a]=\left[0_{x}\right]$ for every $x \xrightarrow{a} y$, as proven in exercise 1.2.3.

Proof. As we have already proved points 2 and 4 , we're proving here only 1 and 3 .

1. Given $a, a^{\prime} \in[a]$ we want to show that $-a \sim-a^{\prime}$. In fact, if $F(s, t)$ is a homotopy between $a$ and $a^{\prime}$, then $G(s, t)=F(s,-t)$ is a homotopy between $-a$ and $-a^{\prime}$.
2. Since in $\operatorname{Hom}_{\mathbf{P} X}(x, y)$ we have that $a+0_{y}=0_{x}+a=a$, the thesis follows from point 2.

Definition 1.2.6. If $X$ is such that for every $x, y \in X$ we have that $\operatorname{Hom}_{\pi X}(x, y)$ contains only one element, then $X$ and $\pi X$ are called 1-connected. If this property doesn't hold hold for the whole space $X$ but holds for each of its path-connected components, we call the space and its fundamental groupoid simply-connected.

Example 1.2.7. If $X$ is a convex normed vector space then it is 1 -connected, since all the paths from $x$ to $y$ are homotopic. In fact, given $a, b \in \operatorname{Hom}_{\mathbf{P} X}(x, y)$ we have that $F(s, t)=(1-s) a(t)+s b(t)$ is well defined for the convexity (since it connects the points of path $a$ to the points of path $b$ via segments) and is an homomorphism.

Note 1.2 .8 . From now on, we'll simplify the notetion a little bit. We'll call our groupoids with simple capital letters $G, H, \ldots$ and when we'll write $a \in G$ what we mean is that we have fixed $x, y \in \operatorname{Obj}(G)$ and we are taking $a \in \operatorname{Hom}_{G}(x, y)$.

Definition 1.2.9. Given a groupoid $G$ and a subset $O$ of its objects, it's easy to construct the subgroupoid $H$ of $G$ that has $O$ as objects and is full: simply, for every $x, y \in \operatorname{Obj}(H)$ we take $\operatorname{Hom}_{H}(x, y):=\operatorname{Hom}_{G}(x, y)$. If $O$ consists of only one element $O=\{x\}$ we'll denote the corresponding full subgroupoid as $G(x)$. We call this latter and - in general - every groupoid with only one element a group. In particular, given a topological space $X$ and a point $x \in X$, the group $\pi X(x)$ is called the fundamental group of $X$ at $x$ and - to adhere to the classical algebraic topological writing - we'll denote it with $\pi_{1}(X, x)$.

Definition 1.2.10. The notion of connectedness given in definition 1.2 .6 can be generalized to any kind of groupoid. We say that $G$ is connected if $\operatorname{Hom}_{G}(x, y)$ is nonempty for every $x, y \in \operatorname{Obj}(G)$. The following trivial theorem further characterize this definition in the case of the fundamental groupoid.

Theorem 1.2.11. A fundamental groupoid $\pi X$ is connected if and only if $X$ is pathconnected.

Proof. This theorem simply follows from the definitions of the fundamental groupoid and of path-connected spaces.

Definition 1.2.12. Given an object $x_{0} \in \operatorname{Obj}(G)$, let's consider $O=\{y \in \operatorname{Obj}(G)$ : $\left.\operatorname{Hom}_{G}(x, y) \neq \emptyset\right\}$. We call the full subgroupoid $C\left(x_{0}\right)$ of $G$ whose object set is $O$, the component of $G$ containing $x_{0}$.

Observation 1.2.13. We'd like to simplify the relation between a connected groupoid $G$ and its groups $G(x)$ (where $x \in \operatorname{Obj}(G)$ ), by showing that all those groups are isomorphic, so that it makes sense to refer to what we call the object group of $G$. We'll do this in the next theorem.

Theorem 1.2.14. Given a connected groupoid $G$ and $x_{1}, y_{1}, x_{2}, y_{2} \in \operatorname{Obj}(G)$, there is a bijection

$$
\begin{equation*}
\varphi: \operatorname{Hom}_{G}\left(x_{1}, y_{1}\right) \rightarrow \operatorname{Hom}_{G}\left(x_{2}, y_{2}\right) \tag{1.2.6}
\end{equation*}
$$

which, in case $x_{1}=y_{1} \wedge x_{2}=y_{2}$ is a group isomorphism between $G\left(x_{1}\right)$ and $G\left(x_{2}\right)$. Proof. Let's take $x_{1} \xrightarrow{a} x_{2}$ and $y_{1} \xrightarrow{b} y_{2}$, which exist by the connectedness. We define:

$$
\begin{align*}
& \varphi: \operatorname{Hom}_{G}\left(x_{1}, y_{1}\right) \rightarrow \operatorname{Hom}_{G}\left(x_{2}, y_{2}\right)  \tag{1.2.7}\\
& \psi: \operatorname{Hom}_{G}\left(x_{2}, y_{2}\right) \rightarrow \operatorname{Hom}_{G}\left(x_{1}, y_{1}\right) \tag{1.2.8}
\end{align*}
$$

As:

$$
\begin{array}{r}
\varphi(c)=b+c-a \\
\psi(c)=-b+c+a \tag{1.2.10}
\end{array}
$$

Where we intend as usual that e.g. $c-a$ is $c \circ(-a)$. It is clear that $\varphi \psi=\operatorname{Id}_{\operatorname{Hom}_{G}\left(x_{2}, y_{2}\right)}$ and $\psi \varphi=\operatorname{Id}_{\operatorname{Hom}_{G}\left(x_{1}, y_{1}\right)}$, so $\varphi$ is a bijection. Also, if $x_{1}=y_{1} \wedge x_{2}=y_{2}$ we have that

$$
\begin{equation*}
\varphi(c)=a+c-a:=a_{x_{1}}(c) \tag{1.2.11}
\end{equation*}
$$

Let's show that this is a group isomorphism. For all $c_{1}, c_{2} \in G(x)$ we have:

$$
\begin{align*}
& a_{x_{1}}\left(c_{1}\right)+a_{x_{1}}\left(c_{2}\right)=  \tag{1.2.12}\\
= & a+c_{1}-a+a+c_{2}-a=  \tag{1.2.13}\\
= & a+\left(c_{1}+c_{2}\right)-a=  \tag{1.2.14}\\
= & a_{x_{1}}\left(c_{1}+c_{2}\right) \tag{1.2.15}
\end{align*}
$$

Definition 1.2.15. We'd now like to generalize the notion of 1 -connected groupoid even where no topological space is assumed behind it. We say that a groupoid $T$ is a tree groupoid if for every two objects $x, y \in \operatorname{Obj}(T)$ there is an unique element $a_{y, x}$ in $\operatorname{Hom}_{T}(x, y)$. Notice that given a third object $z$, then for uniqueness

$$
\begin{equation*}
a_{z, x}=a_{y, x}+a_{z, y} \tag{1.2.16}
\end{equation*}
$$

Observation 1.2.16. Given a non-empty set $X$, it's a trivial task to build a tree groupoid $T$ such that $X=\operatorname{Obj}(T)$. We fix one element $a_{y, x}$ for each two $x, y \in X$ and set $\operatorname{Hom}_{T}(x, y):=\left\{a_{y, x}\right\} ;$ finally we just impose that equation 1.2.16 holds.

Observation 1.2.17. Observation 1.2.16 ensure us that a connected groupoid $G$ can contain a wide tree subgroupid $T$. It's clear that, supposing we don't know the morphisms of $G$, given $T$ there are infinitely many possible ways to create a connected groupoid $G$ such that $T$ is one if its wide tree subgroupoids. But if we fix an element $x_{0} \in \operatorname{Obj}(G)$ and we know how $G\left(x_{0}\right)$ is made, then we'll be able to reconstruct the whole structure of $G$. In fact, let's call $t_{x}$ the only element of $\operatorname{Hom}_{T}\left(x_{0}, x\right)$. Now, given $x, y \in \operatorname{Obj}(G)$ and $x \xrightarrow{a} y$, we can write it as

$$
\begin{equation*}
a=t_{y}+c_{a}-t_{x} \text { for some unique } c_{a} \in G\left(x_{0}\right) \tag{1.2.17}
\end{equation*}
$$

For this reason, given a third object $z \in \operatorname{Obj}(G)$ and a $y \xrightarrow{b} z$, we have that:

$$
\begin{align*}
a+b & =\left(t_{z}+c_{b}-t_{y}\right)+\left(t_{y}+c_{a}-t_{x}\right)=  \tag{1.2.18}\\
& =t_{z}+\left(c_{b}+c_{a}\right)-t_{x} \Rightarrow  \tag{1.2.19}\\
& \Rightarrow c_{b+a}=c_{b}+c_{a} \tag{1.2.20}
\end{align*}
$$

### 1.3 Functors

Functors are the main tools used to make categories interact with each other, so to link different algebraic (or topological) structures in a categorical way. At a more abstract level - and leaving out the paradoxical implication that this may have - they could even be regarded as morphisms in the category of categories!

Definition 1.3.1. Given two categories $\mathbf{A}, \mathbf{B}$, a functor $F: \mathbf{A} \rightarrow \mathbf{B}$ is a function that assigns to each object $A \in \operatorname{Obj}(\mathbf{A})$ an object $F(A) \in \operatorname{Obj}(\mathbf{B})$ and to each morphism $A \xrightarrow{f} A^{\prime}$ of $\mathbf{A}$ a morphism $F(A) \xrightarrow{F(f)} F\left(A^{\prime}\right)$ of $\mathbf{B}$, such that

F1 $F$ preserves composition, i.e. $F(f \circ g)=F(f) \circ F(g)$.
F2 $F$ preserves identity morphisms, i.e. $F\left(\operatorname{Id}_{\mathbf{A}, A}\right)=\operatorname{Id}_{\mathbf{B}, F(A)}$.
Sometimes we'll simply write $F A$ and $F f$ for $F(A)$ and $F(f)$.
Observation 1.3.2. From the definition of functor it follows immediately that it preserves the status of being a retraction, co-retraction or isomorphism.

Example 1.3.3. Examples of functors are:

- For every category $\mathbf{A}$ the identity functor Id : $\mathbf{A} \rightarrow \mathbf{A}$.
- For every two categories $\mathbf{A}, \mathbf{B}$, fixed a $B \in \operatorname{Obj}(\mathbf{B})$, we obtain a constant functor $F$ such that

$$
\begin{equation*}
F(A)=B \forall A \in \operatorname{Obj}(\mathbf{A}) \text { and } F(f)=\operatorname{Id}_{\mathbf{B}, B} \forall A \xrightarrow{f} A^{\prime} \tag{1.3.1}
\end{equation*}
$$

- Given any category from 1.1.2 (e.g. Top) we can remove any algebraic or topological structure from its objects via the forgetful functor. E.g. $F$ : Top $\rightarrow$ Set with (denoting a topological space $X$ with the more formal couple $(X, \vartheta)$ of a set of points and a topology) $F((X, \vartheta))=X$ and $F(f)=f$.
- Given two categories $\mathbf{P} X, \mathbf{P} Y$ consider a map $f: X \rightarrow Y$; we have the functor

$$
\begin{equation*}
P_{f}: \mathbf{P} X \rightarrow \mathbf{P} Y \quad P_{f}(x)=f(x) \forall x \in X \tag{1.3.2}
\end{equation*}
$$

and given $a \in \operatorname{Hom}_{\mathbf{P} X}(x, y)$ we take as $P_{f}(a)$ an arbitrary path in $\operatorname{Hom}_{\mathbf{P} Y}(f(x), f(y))$. Note that if $Y=X$ and $f=\operatorname{Id}_{X}$, then $P_{\mathrm{Id}}$ is the identity functor. Also, given the spaces $X, Y, Z$ and the maps $f: X \rightarrow Y$ and $g: Y \rightarrow Z$ we have that $P_{g \circ f}=P_{g} \circ P_{f}$. Basically, this means that $P$ is a functor from Top $\rightarrow$ Cat, where Cat is the category of the categories (we'll leave the logical implications of considering such a category out of our work!). Also, for observation 1.3.2 we have that if $X$ and $Y$ are homeomorfic through $f$, then $\mathbf{P} X$ and $\mathbf{P} Y$ are isomorphic through the functor $P_{f}$.

- Given a topological space $X$, the functor $F: \mathbf{P} X \rightarrow \pi X$ such that

$$
\begin{equation*}
F(x)=x \forall x \in X \text { and } F(a)=[a] \forall a \in \mathbf{P} X \tag{1.3.3}
\end{equation*}
$$

Observation 1.3.4. As we know a groupoid is a category, but we may as well define the category of groupoids, Grpd. Its objects are groupoids and its morphisms are functors between groupoids. So it naturally arises the question wether the application that sends a space $X$ into its fundamental groupoid $\pi X$ is a functor itself. We settle this question in the nex theorem.

Theorem 1.3.5. The function $\pi: \operatorname{Top} \rightarrow \mathbf{G r p d}$ that sends $X$ into $\pi X$ is a functor.
Proof. Given two spaces $X, Y$ and a continuous map $f: X \rightarrow Y$, let's consider the corresponding functor $P_{f}$ as defined in example 1.3.3. Now given $x, x^{\prime} \in X$ and two paths $a, b:[0,1] \rightarrow X$ from $x$ to $x^{\prime}$ within the same homotopy class through homotopy $F:[0,1]^{2} \rightarrow X$, it's easy to check that $f \circ F$ is a homotopy between $f \circ a$ and $f \circ b$. So we have create a function $\pi f: \pi X \rightarrow \pi Y$ defined as

$$
\begin{equation*}
\pi f([a])=[f \circ a] \tag{1.3.4}
\end{equation*}
$$

which is a morphism between the groupoids $\pi X$ and $\pi Y$. Now we have successfully created our $\pi: \mathbf{T o p} \rightarrow \mathbf{G r p d}$ : given a space $X$ it gives its fundamental groupoid $\pi X$ and given a continuous $f: X \rightarrow Y$ it gives the morphism $\pi f$.

Observation 1.3.6. Theorem 1.3.5 and observation 1.3.2 gives us a ready-to-use class of isomorphic fundamental groupoids: in fact, if two spaces are homeomorfic, their fundamental groupoids are isomorphic.

Definition 1.3.7. Given a topological space $X$ and a point $x \in X$ we call pointed space the couple $(X, x)$. Given two pointed spaces $(X, x),(Y, y)$ we call a pointed map a continuous $f: X \rightarrow Y$ such that $f(x)=y$. This gives us the category $\mathbf{T o p}_{\mathbf{p t}}$, with objects the pointed spaces and morphisms the pointed maps between them.

Theorem 1.3.8. The function $\pi_{1}: \operatorname{Top}_{\mathbf{p}} \rightarrow \mathbf{G r p}$ that sends $(X, x)$ into $\pi_{1}(X, x)$ is a functor.

Proof. The proof is analogous at that of theorem 1.3.5. Given a pointed space ( $X, x$ ) we associate it with its fundamental group $\pi_{1}(X, x)$ and given a pointed map $f: X \rightarrow Y$ we associate it to a morphism $\pi_{1} f: \pi_{1}(X, x) \rightarrow \pi_{1}(Y, y)$ again defined as

$$
\begin{equation*}
\pi_{1} f([a])=[f \circ a] \tag{1.3.5}
\end{equation*}
$$

Since the composition of a loop $a$ around $x$ with the pointed map $f$ gives a loop around $y$, we have actually defined a functor $\pi_{1}$.

Definition 1.3.9. We would now like to show that the fundamental groupoid of the product of two spaces is isomorphic to the product of the fundamental groupoids of the two spaces. It may sound quite intuitive what this product of groupoids should be, nonetheless we will give here the general definition of product of two categories $\mathbf{A}, \mathbf{B}$ as the category $\mathbf{A} \times \mathbf{B}$ whose objects class is

$$
\begin{equation*}
\operatorname{Obj}(\mathbf{A}) \times \operatorname{Obj}(\mathbf{B}) \tag{1.3.6}
\end{equation*}
$$

and - for each two objects $\left(A_{1}, B_{1}\right):=C,\left(A_{2}, B_{2}\right):=D$ - its morphisms are:

$$
\begin{equation*}
\operatorname{Hom}_{\mathbf{A} \times \mathbf{B}}(C, D)=\operatorname{Hom}_{\mathbf{A}}\left(A_{1}, A_{2}\right) \times \operatorname{Hom}_{\mathbf{B}}\left(B_{1}, B_{2}\right) \tag{1.3.7}
\end{equation*}
$$

Also the composition of a morphism $\left(a_{1}, b_{1}\right):=c \in \mathbf{A} \times \mathbf{B}$ with a morphism $\left(a_{2}, b_{2}\right):=$ $d \in \mathbf{A} \times \mathbf{B}$ is defined component-wise as the morphism

$$
\begin{equation*}
d \circ c=\left(a_{2} \circ a_{1}, b_{2} \circ b_{1}\right) \tag{1.3.8}
\end{equation*}
$$

while the inverse is simply

$$
\begin{equation*}
c^{-1}=\left(a_{1}^{-1}, b_{1}^{-1}\right) \tag{1.3.9}
\end{equation*}
$$

Luckily enough, with this definition all the good properties of functors one would expect continue to hold. For example, given a category $\mathbf{C}$ and the functors $f_{A}: \mathbf{C} \rightarrow \mathbf{A}$ and $f_{B}: \mathbf{C} \rightarrow \mathbf{B}$, then there is an unique functor $f: \mathbf{C} \rightarrow \mathbf{A} \times \mathbf{B}$ such that composed with the canonical projections it gives back the functors $f_{A}$ and $f_{B}$. Now we are ready to prove the following theorem.

Exercise 1.3.10. Given a category $\mathbf{C}$, we call its dual the category $\mathbf{C}^{\text {op }}$ such that

$$
\begin{align*}
& \operatorname{Obj}\left(\mathbf{C}^{\text {op }}\right)=\operatorname{Obj}(\mathbf{C})  \tag{1.3.10}\\
& \operatorname{Hom}_{\mathbf{C}^{\mathbf{o p}}}(A, B)=\operatorname{Hom}_{\mathbf{C}}(B, A) \tag{1.3.11}
\end{align*}
$$

Furthermore, if we call $f^{*} \in \operatorname{Hom}_{\mathbf{C o p}^{\text {op }}}(A, B)$ the morphism corresponding to $f \in$ $\operatorname{Hom}_{\mathbf{C}}(B, A)$, then the composition law in $\mathbf{C}^{\mathbf{o p}}$ is

$$
\begin{equation*}
g^{*} \circ f^{*}=(f \circ g)^{*} \tag{1.3.12}
\end{equation*}
$$

Given two categories $\mathbf{C}, \mathbf{D}$, we say that $\Gamma: \mathbf{C} \rightarrow \mathbf{D}$ is a contravariant functor if

$$
\begin{align*}
& f \in \operatorname{Hom}_{\mathbf{C}}(A, B) \Rightarrow \Gamma(f) \in \operatorname{Hom}_{\mathbf{D}}(\Gamma(B), \Gamma(A)) \forall A, B \in \operatorname{Obj}(\mathbf{C})  \tag{1.3.13}\\
& \Gamma(g \circ f)=\Gamma(f) \circ \Gamma(g) \forall A, B, C \in \operatorname{Obj}(\mathbf{C}) \forall A \xrightarrow{f} B, B \xrightarrow{g} C \tag{1.3.14}
\end{align*}
$$

Prove that the contravariant functors $\mathbf{C} \rightarrow \mathbf{D}$ are determined by the functors $\mathbf{C}^{\mathbf{o p}} \rightarrow \mathbf{D}$. Proof. Given the functor $F: \mathbf{C}^{\mathbf{o p}} \rightarrow D$, we define $\Gamma: \mathbf{C} \rightarrow \mathbf{D}$ as

$$
\begin{align*}
& \Gamma(A)=F(A) \quad \forall A \in \operatorname{Obj}(\mathbf{C})=\operatorname{Obj}\left(\mathbf{C}^{\mathbf{o p}}\right)  \tag{1.3.15}\\
& \Gamma(f)=F\left(f^{*}\right) \forall A \xrightarrow{f} B \tag{1.3.16}
\end{align*}
$$

Now, applying the definition of dual category and of functor (see definition 1.3.1), we have first of all that

$$
\begin{align*}
& \forall f \in \operatorname{Hom}_{\mathbf{C}}(A, B) \quad f * \in \operatorname{Hom}_{\mathbf{C o p}}(B, A) \Rightarrow  \tag{1.3.17}\\
\Rightarrow & F(f *) \in \operatorname{Hom}_{\mathbf{D}}(F(B), F(A)) \Rightarrow  \tag{1.3.18}\\
\Rightarrow & \Gamma(f) \in \operatorname{Hom}_{\mathbf{D}}(\Gamma(B), \Gamma(A)) \tag{1.3.19}
\end{align*}
$$

that is the first property of contravariance. The second property is soon proved; in fact

$$
\begin{equation*}
\Gamma(g \circ f)=F\left((g \circ f)^{*}\right)=F\left(f^{*} \circ g^{*}\right)=F(f *) \circ F(g *)=\Gamma(f) \circ \Gamma(g) \tag{1.3.20}
\end{equation*}
$$

Theorem 1.3.11. Given the topological spaces $X_{1}, X_{2}$ and $X=X_{1} \times X_{2}$, then $\pi X$ is isomorphic to $\pi X_{1} \times \pi X_{2}$.

Proof. Consider the morphisms from the fundamental groupoid of the product space to the fundamental groupoids of the spaces

$$
\begin{align*}
& \pi p_{1}: \pi X \rightarrow \pi X_{1}  \tag{1.3.21}\\
& \pi p_{2}: \pi X \rightarrow \pi X_{2} \tag{1.3.22}
\end{align*}
$$

defined as the morphisms induced by the canonical (topological) projections from the product space $X$ to the spaces $X_{1}, X_{2}$. As seen in definition 1.3.9 these gives an unique functor $f: \pi X \rightarrow \pi X_{1} \times \pi X_{2}$ such that, composed with the canonical (categorical) projections it gives back $\pi p_{1}$ and $\pi p_{2}$. As it's natural to imagine, such $f$ is

$$
\begin{equation*}
f([a])=\left(\left[p_{1} \circ a\right],\left[p_{2} \circ a\right]\right) \tag{1.3.23}
\end{equation*}
$$

Now we are ready to construct the isomorphism from $\pi X$ to $\pi X_{1} \times \pi X_{2}$ : fixed two points $x=\left(x_{1}, x_{2}\right), y=\left(y_{1}, y_{2}\right) \in X$ we want to show that $f$ induces a bijection

$$
\begin{equation*}
\operatorname{Hom}_{\pi X}(x, y) \rightarrow \operatorname{Hom}_{\pi X_{1}}\left(x_{1}, y_{1}\right) \times \operatorname{Hom}_{\pi X_{2}}\left(x_{2}, y_{2}\right) \tag{1.3.24}
\end{equation*}
$$

In fact, given two paths $a, b \in \operatorname{Hom}_{\pi X}(x, y)$ such that $f([a])=f([b])$ we have that

$$
\begin{equation*}
f([a])=f([b]) \Rightarrow\left(\left[p_{1} \circ a\right],\left[p_{2} \circ a\right]\right)=\left(\left[p_{1} \circ b\right],\left[p_{2} \circ b\right]\right) \Rightarrow \ldots \tag{1.3.25}
\end{equation*}
$$

Now, if we call $F_{1}$ the homotopy between $p_{1} \circ a$ and $p_{1} \circ b$ and $F_{2}$ the homotopy between $p_{2} \circ a$ and $p_{2} \circ b$, the function $F:[0,1]^{2} \rightarrow X$ with

$$
\begin{equation*}
F(s, t)=\left(F_{1}(s, t), F_{2}(s, t)\right) \tag{1.3.26}
\end{equation*}
$$

is a homotopy between $a$ and $b$ and then

$$
\begin{equation*}
\ldots \Rightarrow[a]=[b] \tag{1.3.27}
\end{equation*}
$$

so the induced map is injective. To prove that it is also a surjection, consider any element $\left(a_{1}, a_{2}\right)$ in $\operatorname{Hom}_{\pi X_{1}}\left(x_{1}, y_{1}\right) \times \operatorname{Hom}_{\pi X_{2}}\left(x_{2}, y_{2}\right)$. The element $a=\left(a_{1}, a_{2}\right)$ is in $\operatorname{Hom}_{\pi X}(x, y)$ and it's trivial to see that, by definition, $f([a])=\left(\left[a_{1}\right],\left[a_{2}\right]\right)$.

Theorem 1.3.12. In an analogous way, one can prove that given the pointed spaces $\left(X_{1}, x_{1}\right)$ and $\left(X_{2}, x_{2}\right)$, then

$$
\begin{equation*}
\pi_{1}\left(X_{1}, x_{1}\right) \times \pi_{1}\left(X_{2}, x_{2}\right) \tag{1.3.28}
\end{equation*}
$$

is isomorphic to

$$
\begin{equation*}
\pi_{1}\left(X_{1} \times X_{2},\left(x_{1}, x_{2}\right)\right) \tag{1.3.29}
\end{equation*}
$$

### 1.4 Pushouts

Pushouts are fundamental for our aim, since they are the object that behaves best, among the ones we've encountered by far. In fact, they bring with themselves two desirable properties: commutativity of diagrams (i.e. paths of arrows only depend on their endpoints) and universality (i.e. uniqueness up to isomorphism that is to say, using a more philosophical language, taht we can forget about particular instances of objects and focus on their ontology).

Definition 1.4.1. Given a category $\mathbf{A}$ and $A_{1}, A_{2} \in \operatorname{Obj}(\mathbf{A})$ we call a coproduct of $A_{1}$ and $A_{2}$ a diagram of the type

$$
\begin{equation*}
A_{1} \xrightarrow{i_{1}} A \stackrel{i_{2}}{\longleftarrow} A_{2} \tag{1.4.1}
\end{equation*}
$$

for some $A \in \operatorname{Obj}(\mathbf{A})$, such that for any diagram $A_{1} \xrightarrow{j_{1}} A^{\prime} \stackrel{j_{2}}{\leftarrow} A_{2}-$ again with $A^{\prime} \in \operatorname{Obj}(\mathbf{A})$ - there is a unique $A \xrightarrow{a} A^{\prime}$ such that

$$
\begin{equation*}
a \circ i_{1}=j_{1} \wedge a \circ i_{2}=j_{2} \tag{1.4.2}
\end{equation*}
$$

This condition is expressed in a more concise way with the diagram:


We will usually write that $A=A_{1} \sqcup A_{2}$ and say that $A$ is the coproduct of $A_{1}$ and $A_{2}$.
Note 1.4.2. From now on, when we'll show diagrams in which what is an object, what is a morphism and at which Hom class it belongs to is clear, we'll omit to specify it.

Definition 1.4.3. Given a category $\mathbf{A}$ and $A_{0}, A_{1}, A_{2} \in \operatorname{Obj}(\mathbf{A})$, we call a pushout of $i_{1}$ and $i_{2}$ a diagram


Such that it is commutative - i.e. $u_{1} \circ i_{1}=u_{2} \circ i_{2}-$ and that if there is another commutative diagram

then there exists an unique morphism $A \xrightarrow{a} A^{\prime}$ such that

$$
\begin{equation*}
a \circ u_{1}=v_{1} \wedge a \circ u_{2}=v_{2} \tag{1.4.6}
\end{equation*}
$$

Again there is a more concise notation for this (and, from no on, we will only use such
kind of notations):


We will usually write $A=A_{1} \sqcup_{i_{1}, i_{2}} A_{2}$ and say that $A$ is the pushout of $i_{1}$ and $i_{2}$.
Example 1.4.4. Examples of pushouts are:

- Given $A_{1}, A_{1} \in \operatorname{Obj}(\operatorname{Set})$ with $A_{0}=A_{1} \cap A_{2}$ and $i_{1}, i_{2}$ canonical inclusions, the pushout of $A_{1}$ and $A_{2}$ is $A=A_{1} \cup A_{2}$ where $u_{1}, u_{2}$ are again canonical inclusions.
- If $A_{1}, A_{2} \in \operatorname{Obj}(\mathbf{T o p})$ and $A_{0} \leq A_{1}$ where $i_{1}$ is the canonical inclusion and $i_{2}$ is a continuous map (called the attaching map), then $A=A_{1} \cup_{i_{2}} A_{2}$ is the adjunction space whose set of points is the sets of the classes of $A_{1} \sqcup A_{2}$ according to the relation of identification of $x$ with $i_{2}(x)$ for every $x \in A$ and whose topology is the one induced by the same relation. One can intuitively imagine that $A_{1}$ is being glued on $A_{2}$ via the map $i_{2}$.
- A special case of the above is when $\left(A_{1}, x\right),\left(A_{2}, y\right) \in \operatorname{Top}_{\mathbf{p} \mathbf{t}}, A=\{x\}$ and $i_{2}$ simply identifies $x$ with $y$. In this case the adjunction space turns out to be just the wedge sum of $A_{1}$ and $A_{2}$.

Definition 1.4.5. Given two diagrams


we call a composite (or, better, an horiziontal composite) of them the diagram:


Note 1.4.6. Until now, we've proved all our statements, in order to get the reader accustomed with categorical methods. From now on, we'll omit some technical proof of minor importance. Most of them can be found in [2].

Theorem 1.4.7. The composite of two pushouts is a pushout.

Definition 1.4.8. Given the following diagram:


We call $\underline{A}$ the back square and $\underline{B}$ the front square and suppose they are commutative. If the diagram is itself commutative, we call it a morphism between $\underline{A}$ and $\underline{B}$. The name is not casual; in fact, notice that there is a trivial identity morphism from $\underline{A}$ into itself and that the composition of such morphisms is a morphism itself. So we can consider the category $\mathbf{C}_{\square}$ whose objects are commutative squares and whose morphisms are the ones just defined.

Theorem 1.4.9. Given $\underline{A}, \underline{B} \in \operatorname{Obj}\left(\mathbf{C}_{\square}\right)$, if $\underline{B}$ is a pushout and there is a retraction from $\underline{B}$ to $\underline{A}$, then $\underline{A}$ is also a pushout.

### 1.5 Further properties of the fundamental groupoid

The main result of this section will be to calculate the fundamental groupoid of a space that can be written as the union of two open subspaces, in terms of the fundamental groupoids of those subspaces. We'll also give a way to turn a functor into another one, while respecting its inner structure, by using natural transformations.

Definition 1.5.1. Given a topological space $X$ and the subspaces $X_{0}, X_{1}, X_{2} \leq X$ such that $X_{0}=X_{1} \cap X_{2}$ and $X=\dot{X}_{1} \cup \stackrel{\circ}{X}_{2}$, we call the square $\underline{\mathrm{X}}$ of $X$ the following square


Note that, by basic properties of continuous maps, $\underline{X}$ is a pushout.
Definition 1.5.2. In the same notations of the previous definition, consider a set $A \subseteq X$. It is called a representative in $X_{0}, X_{1}$ and $X_{2}$ if $A$ intersect each pathconnected component of $X_{0}, X_{1}$ and $X_{2}$.

Theorem 1.5.3. In the same notations of the previous definitions, we call $\pi(X, A)$ the groupoid of all the paths in $X$ with endpoints in $A$ and we call $\pi i_{1}, \pi i_{2}, \pi u_{1}, \pi u_{2}$ the maps induced by $i_{1}, i_{2}, u_{1}, u_{2}$ on the appropriate groupoids; so that we have:

$$
\begin{array}{r}
\pi\left(X_{0}, A\right) \xrightarrow{\pi i_{1}} \pi\left(X_{1}, A\right) \\
\pi\left(X_{0}, A\right) \xrightarrow{\pi i_{2}} \pi\left(X_{2}, A\right) \\
\pi\left(X_{1}, A\right) \xrightarrow{\pi u_{1}} \pi(X, A) \\
\pi\left(X_{2}, A\right) \xrightarrow{\pi u_{2}} \pi(X, A) \tag{1.5.5}
\end{array}
$$

Then the following square is a pushout in Grpd:


Observation 1.5.4. In the special case when $X_{0}$ is path connected, theorem 1.5.3 can be used to reconstruct the fundamental group $\pi_{1}\left(X, x_{0}\right)$ for all $x_{0} \in X_{0}$. But what if $X_{0}$ is not path-connected? In this case, the following definitions and the next theorem come in handy.

Definition 1.5.5. Given two categories $\mathbf{C}$ and $\mathbf{D}$ and two functors $F, G: \mathbf{C} \rightarrow \mathbf{D}$ we call a natural transformation from $F$ to $G$ a function

$$
\begin{equation*}
N: \operatorname{Obj}(\mathbf{C}) \rightarrow \operatorname{Hom}_{\mathbf{D}} \tag{1.5.7}
\end{equation*}
$$

that sends the object $A \in \operatorname{Obj}(\mathbf{C})$ to the morphism $N_{A} \in \operatorname{Hom}_{\mathbf{D}}(F(A), G(A))$ in such a way that for all $B \in \operatorname{Obj}(\mathbf{C})$ and all $A \xrightarrow{f} B$ the diagram

commutes.
Example 1.5.6. As an example of natural transformation consider the categories Grp and Set. Let $F, S: \operatorname{Grp} \rightarrow$ Set be - respectively - the forgetful functor and the squaring functor (that maps $G \xrightarrow{f} H$ to $G^{2} \xrightarrow{f^{2}} H^{2}$ ). Also, let $*_{G}: G^{2} \rightarrow G$ be the group operation for every group $G \in \operatorname{Obj}(\mathbf{G r p})$. Since for every group homomorphism $f: G \rightarrow H$, by definition it holds that

$$
\begin{equation*}
f\left(g *_{G} g^{\prime}\right)=f(g) *_{H} f\left(g^{\prime}\right) \tag{1.5.9}
\end{equation*}
$$

then we have that the function $N$ that maps $G \mapsto *_{G}$ is a natural transformation.
Definition 1.5.7. Let $\mathbf{C}, \mathbf{D}$ be two categories such that $\operatorname{Obj}(C)$ is a set. We define the functor category $\mathbf{D}^{\mathbf{C}}$ as the category whose objects are the functors $F: \mathbf{C} \rightarrow \mathbf{D}$ and the morphisms are the natural transformations between them. Here the composition is done componentwise: given the transformations $N$ between $F$ and $G, M$ between $G$ and $H$ we define the transformation $M N$ between $F$ and $H$ as the transformation such that

$$
\begin{equation*}
(M N)_{A}=M_{A} N_{A} \quad \forall A \in \operatorname{Obj}(\mathbf{C}) \tag{1.5.10}
\end{equation*}
$$

Definition 1.5.8. Given two categories $\mathbf{C}$ and $\mathbf{D}$ and two functors $F, G: \mathbf{C} \rightarrow \mathbf{D}$, a natural transformation $N$ from $F$ to $G$ is said to be a natural equivalence (or a homotopy) if $N_{A}$ is an isomorphism for all $A \in \operatorname{Obj}(\mathbf{C})$. The reason why we call it an homotopy is explained by the fact that we can give a more homotopy-fashioned definition of natural equivalence in the sense that it resembles more closely to the definition of homotopy between paths. It is in fact easy to check that $N$ can be considered as a functor $N: \mathbf{C} \times \mathbf{I} \rightarrow \mathbf{D}$ where $\mathbf{I}$ is the tree groupoid for $\{0,1\}$ such that

$$
\begin{equation*}
F(A)=N(A, 0) \wedge G(A)=N(A, 1) \quad \forall A \in \operatorname{Obj}(\mathbf{C}) \tag{1.5.11}
\end{equation*}
$$

$F$ is usally called the initial functor and $G$ the final functor of $N$. It is also easy to check that the natural equivalence is an equivalence relation and so it makes sense to write $F \simeq G$ whenever there is a natural equivalence with initial functor $F$ and final functor $G$. In this case, $F$ and $G$ are said to be homotopic.

Observation 1.5.9. It's quite easy (but a little bit technical) to see that the fundamental groupoid and the fundamental group are preserved by natural equivalence. This means that given $X, Y \in \operatorname{Obj}(\mathbf{T o p})$, if $X \simeq Y$ then $\pi X \simeq \pi Y$ and given $(X, x),(Y, y) \in \operatorname{Obj}\left(\mathbf{T o p}_{\mathbf{p t}}\right)$, if $(X, x) \simeq(Y, y)$ then $\pi_{1}(X, x) \simeq \pi_{1}(Y, y)$.

Exercise 1.5.10. Two categories $\mathbf{C}, \mathbf{D}$ are said to be equivalent if there are two functors

$$
\begin{equation*}
F: \mathbf{C} \rightarrow \mathbf{D}, \quad G: \mathbf{D} \rightarrow \mathbf{C} \tag{1.5.12}
\end{equation*}
$$

such that $F \circ G \simeq \operatorname{Id}_{\mathbf{D}}$ and $G \circ F \simeq \operatorname{Id}_{\mathbf{C}}$. Now, consider a field $K$ and the category $\operatorname{Lin}_{\mathbf{b}}$ as defined in example 1.1.2, with a small difference: its objects are couples
$\left(V, \mathscr{B}_{V}\right)$ where $V$ is a finite-dimensional vector spaces over $K$ and $\mathscr{B}_{V}$ is a base for $V$; its morphisms are linear maps between the spaces. Let $\mathbf{L}$ be the category defined as follows: its objects are positive natural numbers and for every $m, n \in \mathbb{N}^{+}$the morphisms between $n$ and $m$ are the $n \times m$ matrices with entries in $K$, composed by matrix multiplication (when possible). Prove that $\mathbf{L i n}_{b}$ and $\mathbf{L}$ are equivalent.

Proof. Let's consider the following two functors

- The functor $F: \mathbf{L} \rightarrow \mathbf{L i n}_{\mathbf{b}}$ is such that

$$
\begin{equation*}
\forall n \in \operatorname{Obj}(\mathbf{L})=\mathbb{N} \quad F(n)=\left(K^{n}, \mathscr{E}_{n}\right) \tag{1.5.13}
\end{equation*}
$$

where $\mathscr{E}_{n}$ is the canonical base of $K^{n}$

$$
\begin{align*}
& \forall n, m \in \operatorname{Obj}(\mathbf{L})=\mathbb{N}^{+}, \forall M \in \operatorname{Hom}_{\mathbf{L}}(n, m)=K^{n \times m} \\
& F(M)=\varphi:\left(K^{n}, \mathscr{E}_{n}\right) \rightarrow\left(K^{m}, \mathscr{E}_{m}\right) \tag{1.5.14}
\end{align*}
$$

where $\varphi$ is the linear map associated with $M$ via the canonical bases.

- The functor $G: \mathbf{L i n}_{\mathbf{b}} \rightarrow \mathbf{L}$ is such that

$$
\begin{equation*}
\forall\left(V, \mathscr{B}_{V}\right) \in \operatorname{Obj}\left(\operatorname{Lin}_{\mathbf{b}}\right) \quad G(V)=\operatorname{dim}(V)=\left|\mathscr{B}_{V}\right| \tag{1.5.15}
\end{equation*}
$$

and

$$
\begin{align*}
& \forall\left(V, \mathscr{B}_{V}\right),\left(W, \mathscr{B}_{W}\right) \in \operatorname{Obj}\left(\operatorname{Lin}_{\mathbf{b}}\right), \forall \varphi: V \rightarrow W \\
& F(\varphi)=M \in K^{\operatorname{dim}(V) \times \operatorname{dim}(W)} \tag{1.5.16}
\end{align*}
$$

where $M$ is the matrix associated with the linear map $\varphi$, via the bases $\mathscr{B}_{V}$ and $\mathscr{B}_{W}$.

Now consider that, for every space $\left(V, \mathscr{B}_{V}\right)$ with $\operatorname{dim}(V)=n$ the map $F \circ G$ sends

$$
\begin{equation*}
V \mapsto n \mapsto K^{n} \tag{1.5.17}
\end{equation*}
$$

but since two spaces with the same dimension are isomorphic, this mean that ( $F \circ$ $G) \upharpoonright \operatorname{Obj}(\mathbf{L}) \simeq \mathrm{Id}_{\mathbf{L i n}_{\mathbf{b}}} \upharpoonright \operatorname{Obj}\left(\mathbf{L i n}_{\mathbf{b}}\right)$. Now for the morphisms: for every linear map
$\varphi:\left(V, \mathscr{B}_{V}\right) \rightarrow\left(W, \mathscr{B}_{W}\right), F \circ G$ sends

$$
\begin{equation*}
\varphi \mapsto M \mapsto \psi \tag{1.5.18}
\end{equation*}
$$

where $M$ is the matrix associated with $\varphi$ via the bases $\mathscr{B}_{V}$ and $\mathscr{B}_{W}$ and $\psi: K^{n} \rightarrow K^{m}$ is the linear application associated with $M$ via the canonical bases. Since for every two space with the same dimension is always possible to find an isomorphism between them that sends a fixed base into another fixed base, we have proved that $F \circ G \simeq \operatorname{Id}_{\text {Lin }_{\mathrm{b}}}$. Similarly, for all $n \in \mathbb{N}^{+}$, the map $G \circ F$ sends

$$
\begin{equation*}
n \mapsto\left(K^{n}, \mathscr{E}_{n}\right) \mapsto m \tag{1.5.19}
\end{equation*}
$$

where $n=\operatorname{dim}\left(K^{n}\right)=m$. Also, for every $n, m \in \mathbb{N}^{+}$and $M \in K^{n \times m}, G \circ F$ sends

$$
\begin{equation*}
M \mapsto \varphi \mapsto M^{\prime} \tag{1.5.20}
\end{equation*}
$$

where $\varphi:\left(K^{n}, \mathscr{E}_{n}\right) \rightarrow\left(K^{m}, \mathscr{E}_{m}\right)$ is associated to $M$ via the canonical bases and $M^{\prime} \in$ $K^{n \times m}$ is the matrix associated with $\varphi$ again via the canonical bases and hence, from basic linear algebra theorems, it follows that $M=M^{\prime}$. So we have finally proved that $G \circ F=\mathrm{Id}_{\mathbf{L}}$ and this finally means that $\mathbf{L}$ and $\mathbf{L i n}_{\mathbf{b}}$ are equivalent.

Definition 1.5.11. In the notations of exercise, if two topological spaces $X$ and $Y$ are equivalent, they are usually said to be homotopic spaces through an homotopy equivalence, or to have the same homotopy type. A space that has the same homotopic type of a point - that is, of a space consisting of only one point - is called contratible.

Theorem 1.5.12. A space $X$ is contractible if and only if the identity map $\operatorname{Id}_{X}: X \rightarrow$ $X$ is homotopic to a costant map.

Proof. Suppose that $X$ is contractible, since it is homotopic to $\{y\}$ via the equivalence $f: X \rightarrow\{y\}$ and let $g:\{y\} \rightarrow X$ be its inverse. By definition of homotopy we have that $\mathrm{Id}_{X} \simeq g \circ f$ and since both $f$ and $g$ are trivially constant, the identity is homotopic to a constant map. On the other hand if there exists a map

$$
\begin{equation*}
f: X \rightarrow X \quad: \quad \forall x \in X \quad f(x)=x_{0} \tag{1.5.21}
\end{equation*}
$$

that is homotopic to the identity, then we can consider the space $\left\{x_{0}\right\}$, the canonical inclusion $i:\left\{x_{0}\right\} \rightarrow X$ and the map $g: X \rightarrow\left\{x_{0}\right\}$ - which is the only map from $X$ into $\left\{x_{0}\right\}$. Since we have that $g \circ i=\operatorname{Id}_{\left\{x_{0}\right\}}$ and $i \circ g \simeq \operatorname{Id}_{X}$, we realized the definition of homoopty between $X$ and $\left\{x_{0}\right\}$ and so $X$ is contractible.

Definition 1.5.13. Given two categories $\mathbf{C}$ and $\mathbf{D}$ and a subcategory $\mathbf{C}$ ' of $\mathbf{C}$, we say that a homotopy $N$ between $F$ and $G$ is a homotopy rel $\mathbf{C}^{\prime}$ if $N$ is constant on $\mathbf{C}^{\prime}$, where $F, G: \mathbf{C} \rightarrow \mathbf{D}$ are functors. We will simply write $F \simeq G$ rel $\mathbf{C}^{\prime}$.

Definition 1.5.14. Given a category $\mathbf{C}$ and one of its subcategories $\mathbf{C}^{\prime}$, we say that $\mathbf{C}^{\prime}$ is a deformation retract of $\mathbf{C}$ if, called $i: \mathbf{C}^{\prime} \rightarrow \mathbf{C}$ the canonical inclusion, it holds that

$$
\begin{equation*}
\exists r: \mathbf{C} \rightarrow \mathbf{C}^{\prime} \text { functor }:(i \circ r) \simeq \operatorname{Id}_{\mathbf{C}} \text { rel } \mathbf{C}^{\prime} \tag{1.5.22}
\end{equation*}
$$

In this case, $r$ is called a deformation retraction from $\mathbf{C}$ to $\mathbf{C}^{\prime}$.
Theorem 1.5.15. In the same notations of the previous definitions, consider a set $A^{\prime} \subset A \cap X_{1}$ representative in $X_{1}$ and let $A_{1}=A^{\prime} \cup A-X_{1}$. Then there exists a pushout

such that both $r$ and $r^{\prime}$ are deformation retractions.

### 1.6 The fundamental group of the circle

In this section, we'll take a short brake to prove a classical result of algebraic topology: the computation of the fundamental group of the circle $S^{1}$.

Theorem 1.6.1. Consider the unit circle $S^{1}$ in the complex plane (i.e. $\mathbb{R}^{2}$ where we
identify $(a, b)$ with $a+i b \in \mathbb{C})$. Then

$$
\begin{equation*}
\pi_{1}\left(S^{1}, 1\right) \simeq \mathbb{Z} \tag{1.6.1}
\end{equation*}
$$

Proof. Let:

$$
\begin{align*}
& X_{1}=S^{1}-\{i\}  \tag{1.6.2}\\
& X_{2}=S^{1}-\{-i\}  \tag{1.6.3}\\
& X_{0}=X_{1} \cap X_{2}  \tag{1.6.4}\\
& A=\{-1,1\}  \tag{1.6.5}\\
& A_{1}=\{1\} \tag{1.6.6}
\end{align*}
$$

So, $X_{1}$ and $X_{2}$ are just an unitary circle without a point, which is homeomorphic to $(0,1)$ and so simply connected. $X_{0}$ is the unitary circle with two holes so is just the sum of two simply connected components. Now just notice that being simply connected means that any two paths with the same endpoints are equivalent, that is to say that the fundamental groupoid of $X_{1}$ and $X_{2}$ has only one morphism for each couple of objects, so it is the tree groupoid I. Meanwhile, $X_{0}$ has two simply connected components, so in an analogous fashion, its fundamental groupoid is just the trivial discrete groupoid with two elements (say $\{0,1\}$ ), that we denote by J. So, by theorem 1.5.15, we have the following pushout (denoting with $\mathbf{K}$ the trivial group with just one element - say $\{0\}$ )

where $g$ is completely defined by just fixing one value. Now, by definition of pushout, we know that for every morphism $f: \mathbf{I} \rightarrow \mathbb{Z}$ (where $\mathbb{Z}$ is regarded as a group), there is a unique $h: \pi_{1}\left(S^{1}, 1\right) \rightarrow \mathbb{Z}$ such that $h \circ g=f$. But since $g$ is defined by one value (say $g(\iota)=\varphi$ ), this means that there a unique $h$ such that $h(\varphi)=f(\iota)$ and we can suppose without loss of generality that $f(\iota)=1 \in \mathbb{Z}$ (just by choosing the appropriate
$f)$. Now consider the morphism

$$
\begin{equation*}
k: \mathbb{Z} \rightarrow \pi_{1}\left(S^{1}, 1\right) \text { with } k(n)=n \varphi \tag{1.6.8}
\end{equation*}
$$

This morphism satisfies the relation we imposed on $h$ and so, by uniqueness, it must hold that $k \circ h=\operatorname{Id}_{\pi_{1}\left(S^{1}, 1\right)}$. So $k$ is the desired isomorphism.

Exercise 1.6.2. Find the fundamental group of the torus, $S^{1} \times S^{1}$
Proof. From theorems 1.6 .1 and 1.3 .12 it immediately follows that it is $\mathbb{Z} \times \mathbb{Z}$. In case one doesn't know that this group is abelian, it may be interesting to watch the animated proof of this fact by the University of Hannover. ${ }^{1}$

### 1.7 Fibrations of groupoids and cofibrations of spaces

We'll now give a characterization of what inclusion of spaces we are willing to consider as "well-behaved": we'll call them cofibrations (well, an homotopist may disagree on their well-behavedness but we're homologist, aren't we?).

Note 1.7.1. In the following we will swap very often between groupoids as categories and as objects of the category Grpd. To make the process not too tedious, let's decide that - given two groupoids $A, B$ - whenever we say

- "a morphism $f: A \rightarrow B$ " we mean that $f \in \operatorname{Hom}_{\operatorname{Grpd}}(A, B)$
- "an object $x$ of $A$ " we mean that $x \in \operatorname{Obj}(A)$
- "an element $a$ in $A$ " - or simply $a \in A$ - we mean that $a \in \operatorname{Hom}_{A}$; if we say that $a$ has starting point $x$ we mean that $a \in \operatorname{Hom}_{A}(x,-)$, while if we say it has ending point $x$ we mean that $a \in \operatorname{Hom}_{A}(-, x)$.
- given $a, b \in A$ if the ending point of $a$ is the starting point of $b$ we let $b+a:=b \circ a$ Definition 1.7.2. Given two groupoids $E, B$ and a morphism $p: E \rightarrow B$, we say that it is a fibration if

$$
\begin{equation*}
\forall x \in \operatorname{Obj}(E) \forall b \in \operatorname{Hom}_{B}(p(x),-) \exists e \in \operatorname{Hom}_{A}(x,-): p+e=b \tag{1.7.1}
\end{equation*}
$$

[^0]Exercise 1.7.3. If $E, B$ are groups, prove that the fibrations from $E$ to $P$ are all and only the surjections.

Proof. Let $\operatorname{Obj}(E)=\{x\}$ and $\operatorname{Obj}(B)=\{y\}$, then there's only one way of choosing $x$ and $p(x)$ and so we can just write $p(e)$ for $(p \circ e)(x)$ and $b$ for $b(x)$ and those values completely define the two maps. So, the condition for being a fibration becomes

$$
\begin{equation*}
\forall b \in B \quad \exists e \in E \quad: \quad p(e)=b \tag{1.7.2}
\end{equation*}
$$

that is the same condition for $p$ to be surjective.
Definition 1.7.4. Given the groupoids $B, E$, the morphism $p: E \rightarrow B$ and an object $u$ of $B$ we denote with $p^{-1}[u]$ the subgroupoid of $E$ that has

- $\operatorname{Obj}\left(p^{-1}[u]\right)=\{x \in \operatorname{Obj}(E) \quad: \quad p(x)=u\}$
- $\operatorname{Hom}_{p^{-1}[u]}=\left\{e \in E \quad: \quad p+e=0_{u}\right\}$

Theorem 1.7.5. Given the groupoids $B, E$ and the fibration $p: E \rightarrow B$, for each $b \in \operatorname{Hom}_{B}(u, v)$ there exsits a function

$$
\begin{equation*}
\underline{b}: \pi_{0} p^{-1}[u] \rightarrow \pi_{0} p^{-1}[v] \tag{1.7.3}
\end{equation*}
$$

where $\pi_{0} G$ is the set of the components of a groupoid $G$ (cfr. definition 1.2.12), such that

- if $b$ is a zero object, then $\underline{b}$ is the identity
- $\underline{c+b}=\underline{c}+\underline{b}$ whenever it is possible to compose $c$ and $b$
- $\underline{b}$ is bijective for all $b \in B$

Definition 1.7.6. In the notations of definition 1.7.4, we express the condition realized via the previous theorem by saying that the groupoid $B$ acts on the family of sets

$$
\begin{equation*}
\left\{\pi_{0} p^{-1}[u]: u \in \operatorname{Obj}(B)\right\} \tag{1.7.4}
\end{equation*}
$$

Observation 1.7.7. In definition 1.2.2 we defined the concept of homotopy between paths within a topological space. This concept can be extended to the one of homotopy
between functions from a space $X$ to a space $Y$. Given two functions $f, g: X \rightarrow Y$ an homotopy between $f$ and $g$ is a map

$$
\begin{equation*}
F: X \times[0,1] \rightarrow Y \tag{1.7.5}
\end{equation*}
$$

such that

$$
\begin{equation*}
F(x, 0)=f(x) \wedge F(x, 1)=g(x) \quad \forall x \in X \tag{1.7.6}
\end{equation*}
$$

Definition 1.7.8. Given two topological spaces $A, X$ and a map $i: A \rightarrow X$, we say that $i$ is a cofibration if for all the spaces $Y$, all maps $f: X \rightarrow Y$ and all homotopies $F: A \times[0,1] \rightarrow Y$ such that

$$
\begin{equation*}
F(a, 0)=(f \circ i)(a) \quad \forall a \in A \tag{1.7.7}
\end{equation*}
$$

there is an homotopy $G: X \times[0,1] \rightarrow Y$ such that

$$
\begin{equation*}
G(x, 0)=f(x) \quad \forall x \in X \tag{1.7.8}
\end{equation*}
$$

and

$$
\begin{equation*}
\left(G \circ\left(i \times \operatorname{Id}_{[0,1]}\right)\right)(x, t)=F(x, t) \quad \forall x \in X \forall t \in[0,1] \tag{1.7.9}
\end{equation*}
$$

When $A \subseteq X$, we say that $i$ extends $f \circ i$ to $f$ and $G \circ\left(i \times \operatorname{Id}_{[0,1]}\right)$ to $F$; we also say that $A$ and $X$ have the homotopy extension property.

Observation 1.7.9. The choice of the names fibration and cofibration for two things that are apparently quite different is not at all casual. The next definitions and theorems will be devoted to expose the link between those two construtctions

Definition 1.7.10. If we consider the maps $X \rightarrow Y$ as points of the space $Y^{X}$ and the homotopies between them as paths in the same space, we can use definition 1.2.2 to find some sort of homotopies of homotopies. So we say that two homotopies

$$
\begin{equation*}
F, G: X \times[0,1] \rightarrow Y \tag{1.7.10}
\end{equation*}
$$

from $f: X \rightarrow Y$ to $g: X \rightarrow Y$ are homotopic rel endmaps $f, g$ if they are homotopic rel endpoints $f, g$ in $Y^{X}$. Explicitely, that is to say that there is a function
$H: X \times[0,1]^{2} \rightarrow Y$ such that

$$
\begin{align*}
& H(x, s, 0)=F(x, s) \wedge H(x, s, 1)=G(x, s) \forall(x, s) \in X \times[0,1]  \tag{1.7.11}\\
& H(x, 0, t)=f(x) \wedge H(x, 1, t)=g(x) \forall(x, t) \in X \times[0,1] \tag{1.7.12}
\end{align*}
$$

We call the fundamental groupoid $\pi Y^{X}$ of $Y^{X}$ the track groupoid of $X, Y$. Notice that by definition, the components of this groupoid (that we should call $\pi_{0} \pi Y^{X}$ according to the nomenclature of theorem 1.2.2, but that we'll just call $[X, Y]$ for short) are the class of homotopy of the maps in $Y^{X}$.

Definition 1.7.11. Given the maps $i: A \rightarrow X, h: Y \rightarrow Z$, consider the functions

$$
\begin{align*}
& i^{*}: \pi Y^{X} \rightarrow \pi Y^{A}  \tag{1.7.13}\\
& h_{*}: \pi Y^{X} \rightarrow \pi Z^{X} \tag{1.7.14}
\end{align*}
$$

that act on objects (maps) as

$$
\begin{align*}
& i^{*}(f)=f+i  \tag{1.7.15}\\
& h_{*}(f)=h+f \tag{1.7.16}
\end{align*}
$$

and on morphisms (homotopy classes) as

$$
\begin{align*}
& i^{*}([F])=\left[F \circ\left(i \times \operatorname{Id}_{[0,1]}\right)\right]  \tag{1.7.17}\\
& h_{*}([F])=[h \circ F] \tag{1.7.18}
\end{align*}
$$

It can be easily checked that $i^{*}$ and $h_{*}$ can be considered both as morphisms in Grpd and as functors from a track groupoid to an other and furthermore, they preserve homotopy. $i^{*}$ and $h_{*}$ are called the induced morphisms of $i$ and $h$.

Theorem 1.7.12. Given the spaces $A$ and $X$ and the cofibration $i: A \rightarrow X$, then the induced morphsim $i^{*}: \pi Y^{X} \rightarrow \pi Y^{A}$ is a fibration, for every space $Y$.

Proof. Given a map $f: X \rightarrow Y$, consider any homoptopy $F$ in $\pi Y^{A}$ of initial map $f+i$. Since $i$ is a cofibration, this means that there is an homotopy $G$ in $\pi Y^{X}$ with initial map $f$ and such that

$$
\begin{equation*}
G+\left(i \times \operatorname{Id}_{[0,1]}\right)=F \tag{1.7.19}
\end{equation*}
$$

But then $i^{*}+G=F$ and so $i^{*}$ is a fibration.

## PRODUCTS AND QUOTIENTS OF GROUPOIDS

### 2.1 Universal morphisms and universal groupoids

The main purpose of this section is to find out a way to change the objects of a groupoid and end up with another nice groupoid, by the mean of a morphism, where by "nice" we mean that the morphism we used has the unviversal property.

Definition 2.1.1. Given a groupoid $G$, a set $X \neq \emptyset$ and a function $\sigma: \operatorname{Obj}(G) \rightarrow X$, fixed two elements $x, x^{\prime} \in X$ and a number $n \in \mathbb{N}^{+}$, we define a word of length $n$ from $x$ to $x^{\prime}$ as a sequence

$$
\begin{equation*}
a=\left\langle a_{1}, \ldots, a_{n}\right\rangle \tag{2.1.1}
\end{equation*}
$$

where $a_{i} \in \operatorname{Hom}_{G}\left(x_{i}, x_{i}^{\prime}\right) \forall i \leq n$, such that

1. $x_{i}^{\prime} \neq x_{i+1} \forall i<n$
2. $\sigma\left(x_{i}^{\prime}\right)=\sigma\left(X_{i+1}\right) f a i<n$
3. $\sigma\left(x_{1}\right)=x, \sigma\left(x_{n}^{\prime}\right)=x^{\prime}$
4. $a_{i} \neq \operatorname{Id}_{G, x_{i}} \forall i \leq n$

Definition 2.1.2. Given the elements of the previous definition and using a multiplicative notation for groupoids, we construct a groupoid $U$, called the universal
groupoid, with

$$
\begin{equation*}
\operatorname{Obj}(U)=X \tag{2.1.2}
\end{equation*}
$$

and

$$
\begin{equation*}
\forall x, x^{\prime} \in X \operatorname{Hom}_{U}\left(x, x^{\prime}\right)=\left\{\left\langle a_{1}, \ldots, a_{n}\right\rangle \text { from } x \text { to } x^{\prime}, \forall n \in \mathbb{N}^{+}\right\} \tag{2.1.3}
\end{equation*}
$$

where we adopt the convention that, whenever $x=x^{\prime}$ we also include the empty word $\left\rangle_{x}\right.$ in $\operatorname{Hom}_{U}\left(x, x^{\prime}\right)$ and we assume that if $x \neq y$ then $\left\rangle_{x} \neq\langle \rangle_{y}\right.$. We define the composition (that is, multiplication) in this groupoid by induction on the length of the words, according to the following rules:

1. $\forall a \in \operatorname{Hom}_{U}\left(x, x^{\prime}\right) \quad\langle \rangle_{x^{\prime}} \cdot a:=a$ and $a \cdot\left\rangle_{x}:=a\right.$
2. $\forall a \in \operatorname{Hom}_{U}\left(x, x^{\prime}\right), \forall b \in \operatorname{Hom}_{U}\left(x^{\prime}, x^{\prime \prime}\right)$ with

$$
\begin{align*}
a & =\left\langle a_{1}, \ldots, a_{n}\right\rangle \wedge a_{i} \in \operatorname{Hom}_{G}\left(x_{i}, x_{i}^{\prime}\right) \forall i \in\{1, \ldots, n\}  \tag{2.1.4}\\
b & =\left\langle b_{1}, \ldots, b_{m}\right\rangle \wedge b_{i} \in \operatorname{Hom}_{G}\left(y_{i}, y_{i}^{\prime}\right) \forall i \in\{1, \ldots, m\} \tag{2.1.5}
\end{align*}
$$

we define

$$
b \cdot a:= \begin{cases}\left\langle a_{1}, \ldots, a_{n}, b_{1}, \ldots, b_{m}\right\rangle & \text { if } y_{1} \neq x_{n}^{\prime}  \tag{2.1.6}\\ \left\langle a_{1}, \ldots, a_{n-1}, b_{1} \cdot a_{n}, b_{2}, \ldots, b_{m}\right\rangle & \text { if } y_{1}=x_{n}^{\prime} \wedge b_{1} \cdot a_{n} \neq \operatorname{Id}_{G, x_{n}} \\ \left\langle a_{1}, \ldots, a_{n-1}, b_{2}, \ldots, b_{m}\right\rangle \text { (by induction) } & \text { otherwise }\end{cases}
$$

That each element has an inverse is easily shown, since the empty word behaves as an identity and given a word $\left\langle a_{1}, \ldots, a_{n}\right\rangle$ we have that

$$
\begin{align*}
& \left\langle a_{1}, \ldots, a_{n}\right\rangle \cdot\left\langle a_{n}^{-1}, \ldots, a_{1}^{-1}\right\rangle=\langle \rangle_{x}  \tag{2.1.7}\\
& \left\langle a_{n}^{-1}, \ldots, a_{1}^{-1}\right\rangle \cdot\left\langle a_{1}, \ldots, a_{n}\right\rangle=\langle \rangle_{x^{\prime}} \tag{2.1.8}
\end{align*}
$$

Also, with some patience, it's possible to show that associativity holds. Finally, since $U$ depends by both $G$ and $\sigma$, we will sometimes denote it as $U_{\sigma}(G)$.

Definition 2.1.3. Given a groupoid $G$, we define a morphism of groupoids $\bar{\sigma}: G \rightarrow$ $U_{\sigma}(G)$ that is the identity on the objects and acts on the morphisms in the following
way:

$$
\sigma(a)= \begin{cases}\langle a\rangle & \text { if } x \neq x^{\prime} \text { or } x=x^{\prime} \text { and } a \neq \operatorname{Id}_{G, x}  \tag{2.1.9}\\ \langle \rangle_{x} & \text { if } x=x^{\prime} \text { and } a=\operatorname{Id}_{G, x}\end{cases}
$$

Definition 2.1.4. Given two groupoids $G, H$ and a morphism $f: G \rightarrow H$, we say that $f$ is universal if the following square is a pushout:

where here $\operatorname{Obj}(G)$ and $\operatorname{Obj}(H)$ are seen as the full groupoids on the sets $\operatorname{Obj}(G)$ and $\operatorname{Obj}(H)$ with only identities as morphisms and so $f_{\text {Obj }}$ is the naturally induced morphism between those two groupoids, while $i_{G}$ and $i_{H}$ are the naturally induced inclusions.

Theorem 2.1.5. The mophism $\bar{\sigma}$ of definition 2.1.3 is universal.

### 2.2 Free groupoids and free product of groupoids

Here we'll give a way to produce a new groupoids from two (or many) given ones, by generalizing the notion of free product between groups. In particular, we will see that the "old" algebraic notion of free product between groups is just our coproduct, as we defined it in 1.4.1.

Definition 2.2.1. We define a graph $\Gamma$ as a couple made by a set of objects or vertices $\operatorname{Obj}(\Gamma)$ and, for all $x, y \in \operatorname{Obj}(\Gamma)$ a set of oriented edges $\operatorname{Edg}_{\Gamma}(x, y)$ that are mutually disjoint. A vertex $x$ such that

$$
\begin{equation*}
\operatorname{Edg}_{\Gamma}(x, y)=\operatorname{Edg}_{\Gamma}(y, x)=\emptyset \quad \forall y \in \operatorname{Obj}(\Gamma) \tag{2.2.1}
\end{equation*}
$$

is called a discrete vertex. If all vertices are discrete, the graph is called a discrete graph.

Definition 2.2.2. Given two graphs $\Gamma, \Delta$ a graph morphism $f: \Gamma \rightarrow \Delta$ is an application that sends vertices of $\Gamma$ in vertices of $\Delta$ and edges of $\Gamma$ in edges of $\Delta$. As it's easy to check, graphs with those morphisms form a category, Gph.

Definition 2.2.3. It's quite clear that graphs are almost categories (they only lack the "identity edges" in general), so we'd like to give some categorical-sounding definition for them. Given two graphs $\Gamma, \Delta$, if $\Gamma \subseteq \Delta$ and the inclusion is a morphism we say that $\Gamma$ is a subgraph of $\Delta$. It is called full if $\operatorname{Obj}(\Gamma)=\operatorname{Obj}(\Delta)$ and wide if

$$
\begin{equation*}
\forall x, y \in \operatorname{Obj}(\Gamma) \operatorname{Edg}_{\Gamma}(x, y)=\operatorname{Edg}_{\Delta}(x, y) \tag{2.2.2}
\end{equation*}
$$

Observation 2.2.4. Notice that every category and in particular every groupoid $G$ can be viewed as a graph $\Gamma$ with $\operatorname{Obj}(\Gamma)=\operatorname{Obj}(G)$ and $\operatorname{Edg}(\Gamma)=\operatorname{Hom}(G)$. Analogously a functor between groupoids can be viewed as a graph morphism. Notice finally that there's no need to consider the whole groupoid as a graph, but we can simply take part of it (i.e. a subset of its objects and their morphisms) and so talk about a graph in a groupoid. Of course, in general, this won't be a subgroupoid.

Definition 2.2.5. Given a groupoid $G$ and a graph $\Gamma$ in $G$, the subgroupoid generated by $\Gamma$ is the smallest subgroupoid of $G$ that contains $\Gamma$.

Definition 2.2.6. A groupoid $G$ is said to be free if there is a graph $\Gamma$ in $G$ such that $\operatorname{Obj}(\Gamma)=\operatorname{Obj}(G)$ and whenever is given a groupoid $H$ and a graph morphism $f: \Gamma \rightarrow H$ there is only one way to extend $f$ into a morphism of groupoids $G \rightarrow H$. In particular, we say that $G$ is free on $\Gamma$.

Theorem 2.2.7. Given two groupoids $G, H$ there exists a groupoid $K$ and two morphisms $f_{1}: G \rightarrow K$ and $f_{2}: H \rightarrow K$ such that for every groupoid $L$ and for every morphisms $g: G \rightarrow L$ and $h: H \rightarrow L$ such that $f$ and $g$ are the same on $\operatorname{Obj}(G) \cap \operatorname{Obj}(H)$, there is an unique morphism $k: K \rightarrow L$ such that $k \circ f_{1}=g$ and $k \circ f_{2}=h$.

Proof. Consider the set

$$
\begin{equation*}
X=\operatorname{Obj}(G) \cup \operatorname{Obj}(H) \tag{2.2.3}
\end{equation*}
$$

and the function

$$
\begin{equation*}
\sigma: \operatorname{Obj}(G) \sqcup \operatorname{Obj}(H) \rightarrow X \tag{2.2.4}
\end{equation*}
$$

obtained as the union of the two canonical inclusions $\operatorname{Obj}(G) \rightarrow X$ and $\operatorname{Obj}(H) \rightarrow X$. Of course $\sigma$ is a surjection and - in particular - is a bijection if $\operatorname{Obj}(G) \sqcup \operatorname{Obj}(H) \leftrightarrow$ $\operatorname{Obj}(G) \cup \operatorname{Obj}(H)$, that is $\operatorname{Obj}(G) \cap \operatorname{Obj}(H)=\emptyset$. Now let $K=U_{\sigma}(G \sqcup H)$ and consider $\bar{\sigma}: G \sqcup H \rightarrow K$ as defined in 2.1.3. So, we can reduce the thesis in proving that $f_{1}$ and $f_{2}$ are universal; but this is clear, since the diagram

implies that $f_{1}=\bar{\sigma} \circ i_{G}$ and $f_{2}=\bar{\sigma} \circ i_{H}$, where $i_{G}$ and $i_{H}$ are the canonical inclusions of respectively $G$ and $H$ in $G \sqcup H$.

Definition 2.2.8. The group $K$ of theorem 2.2 .7 is called the free product of $G$ and $H$ and is denoted as $G * H$.

Observation 2.2.9. If $G, H$ are groups, their free product is just their coproduct as can be clearly seen by noticing that $f_{1}$ and $f_{2}$ have the universal property if and only if the following square is a pushout - a property that anyway holds in general for groupoids:


Exercise 2.2.10. Many of the notions introduced in this chapter have a nice algebraic interpretation. For example, if we consider in particular groups, given a group $G$ and a graph $\Gamma$ in $G$, the subgroup $H$ of $G$ generated by $\Gamma$ - that, as we defined it is the smallest subgroup of $G$ that contains $\Gamma$ - can be seen as the group whose elements are all the possible finite multiplications of elements (that is, morphisms) $\Gamma$ and their inverses. Furthermore, given a set $X$, we call a group action of $G$ over $X$ a function
$a: G \times X \rightarrow X$ such that

$$
\begin{align*}
& a(e, x)=x \quad \forall x \in X  \tag{2.2.7}\\
& a(g h, x)=a(g, a(h, x)) \quad \forall x \in X, \forall g, h \in G \tag{2.2.8}
\end{align*}
$$

where $e \in G$ is the unit element of $G$. Now, given subgroups $G_{1}, \ldots, G_{n}$ of $G$ such that all of them generates $G$ (that is, the subgroup generated by them is the whole $G)$, suppose that $G$ acts on $X$ and that there are $X_{1}, \ldots, X_{n} \subseteq X$ and an element $x \in X \backslash \bigcup_{i=1}^{n} X_{i}$ such that, for all $g \in G_{i}$ with $g \neq e$ and for all $i \in\{1, \ldots, n\}$

1. $a\left(g, X_{j}\right) \subseteq X_{i}$ if $j \neq i$
2. $a(g, x) \in X_{i}$

Show that $G$ is the free product $G_{1} * \ldots * G_{n}$.
Proof. For what we said, any element $g \in G$ can be written as a product of elements of the various $G_{i}$ :

$$
\begin{equation*}
g=g_{1} \cdot \ldots \cdot g_{m} \text { with } g_{i} \in G_{n_{i}} \text { for some } n_{i} \tag{2.2.9}
\end{equation*}
$$

Since in such representation we can "collapse" consecutive elements if they belong to the same $G_{n_{i}}$ (or if one of them is the unit element) my multiplying them and taking the result, we can suppose without loss of generality that $g$ is in the form

$$
\begin{equation*}
g=g_{1} \cdot \ldots \cdot g_{k} \tag{2.2.10}
\end{equation*}
$$

where each $g_{i} \in G_{n_{i}}$ for some $n_{i}, g_{i} \neq e$ and $G_{n_{i}} \neq G_{n_{i+1}}$ for all $i \in\{1, \ldots, k\}$. As noticed in theorem 2.2.7 (generalizing from the case where $n=2$ ) there is a surjective homomorphism

$$
\begin{equation*}
\sigma: \bigsqcup_{i=1}^{n} G_{i} \rightarrow G \tag{2.2.11}
\end{equation*}
$$

Since we want to prove that $G=G_{1} * \ldots * G_{n}$, that is $G=\bigsqcup_{i=1}^{n} G_{i}$, we have to show that $\sigma$ is actually an isomoprhism, so that it is also injective as an homomorphism of groups. This means we have to prove that is kernel is trivial: $\operatorname{ker} \sigma=\{e\}$. Now, given a $g$ as in (2.2.10), by the second hypothesis we have that

$$
\begin{equation*}
a\left(g_{k}, x\right) \in X_{n_{k}} \tag{2.2.12}
\end{equation*}
$$

But then, by the first hypothesis and applying the second again, we get

$$
\begin{equation*}
a\left(g_{k-1}, a\left(g_{k}, x\right)\right) \in X_{n_{k-1}} \tag{2.2.13}
\end{equation*}
$$

and so on, until we obtain

$$
\begin{equation*}
a\left(g_{1}, a\left(\ldots, a\left(g_{k}, x\right)\right)\right) \in X_{n_{1}} \tag{2.2.14}
\end{equation*}
$$

But now notice that $a(e, x)=x$ and for how we chose $x$ this means that $a(e, x) \notin G_{n_{1}}$ and so it's impossible that $\sigma(g)=\sigma\left(g_{1} \cdot \ldots \cdot g_{n}\right)=e$ for all the $g \neq e$. This proves that $\operatorname{ker} \sigma$ is trivial.

### 2.3 Quotient groupoids

Again we'll give a generalization of a well-known group theoretic notion, the one of quotient group. In particular, we'll give the notion of normal subgroupoid and translate the classical algebraic definition in terms of an annihilating morphism.

Definition 2.3.1. Given a groupoid $G$, a subgroupoid $N$ is said to be normal in $G$ if it's wide and for all $x, y \in \operatorname{Obj}(G)$ and $a \in \operatorname{Hom}_{G}(x, y)$

$$
\begin{equation*}
a_{c}(N(x))=N(y) \tag{2.3.1}
\end{equation*}
$$

where $a_{c}$ is the conjugacy function $x \mapsto a x a^{-1}$. The condition (2.3.1) is expressed for short as

$$
\begin{equation*}
a N(x) a^{-1}=N(y) \tag{2.3.2}
\end{equation*}
$$

Definition 2.3.2. Given two groupoids $G, H$ and a graph $\Gamma$ of $G$ a morphism $f: G \rightarrow$ $H$ is said to annihilate $\Gamma$ if $f(\Gamma)$ is a discrete subgroupoid of $H$.

Theorem 2.3.3. Let $G$ be a groupoid and $N$ be a totally disconnected normal subgroupoid of $G$. Then there is a groupoid $M$ and an universal morphism $p: G \rightarrow M$ such that $p$ annihilates $N$ (regarded as a subgraph of $G$ ).

Definition 2.3.4. The groupoid $M$ of theorem 2.3.3 is called a quotient groupoid of $G$ and is denoted by $G / N$.

Observation 2.3.5. There are a lot of similarities between quotient groups in the classic algebraic sense and quotient groupoids. For instance, if given two groupoids $G, H$ and a morphism $f: G \rightarrow H$ we call ker $f$ the largest subgroupoid that is annihilated by $f$, it holds that the canonical morphism

$$
\begin{equation*}
G / \operatorname{ker} f \rightarrow \operatorname{im} f \tag{2.3.3}
\end{equation*}
$$

is an isomorphism.

### 2.4 Adjunction spaces

The last tool we're going to need are adjunction spaces and we study some of their most important properties, that we need to prove Van Kampen's theorem.

Observation 2.4.1. Recall from example 1.4.4 the definition of adjunction space and that we showed, in the same notation of the exercise, that the following square is a pushout:


Where we used the shorter and more meaningful notation

$$
\begin{equation*}
i:=i_{2} \quad f:=i_{1} \quad I:=v_{1} \quad F:=v_{2} \tag{2.4.2}
\end{equation*}
$$

and in the hypothesis that $i$ is a cofibration.
Definition 2.4.2. First of all, we extend the notion of deformation retraction in a topological space. Given $B \subseteq A_{2}$, called $i_{B}: B \rightarrow A_{2}$ the canonical inclusion, we say that a retraction $r$ is a deformation retraction if $i \circ r$ is homotopic to $\operatorname{Id}_{A_{2}}$. We then say that $B$ is a deformation retract of $A_{2}$. It's clear from the definitions of retraction and homotopy that $B$ is a deformation retract of $A_{2}$ if there is a continuous
map

$$
\begin{equation*}
R:[0,1] \times A_{2} \rightarrow A_{2} \quad: \quad R(0,-)=\operatorname{Id}_{A_{2}} \wedge R\left(1, A_{2}\right)=B \tag{2.4.3}
\end{equation*}
$$

called the retracting homotopy.
Definition 2.4.3. Given two spaces $A_{0}$ and $A_{1}$ and a map $f: A_{0} \rightarrow A_{1}$, consider $g: A_{0} \times\{0\} \rightarrow A_{1}$ trivially defined by

$$
\begin{equation*}
g(x, 0)=f(x) \tag{2.4.4}
\end{equation*}
$$

We then define the mapping cylinder of $f$ as the adjunction space

$$
\begin{equation*}
M(f)=A_{1} \cup_{g}\left(A_{0} \times[0,1]\right) \tag{2.4.5}
\end{equation*}
$$

Theorem 2.4.4. Given $B$ which lies midway between $A_{0}$ and $A_{2}\left(A_{0} \subseteq B \subseteq A_{2}\right)$ if $B$ is a deformation retract of $A_{2}$ then $A_{1} \cup_{f} B$ is a deformation retract of $A_{1} \cup_{f} A_{2}$.

Proof. Let $R:[0,1] \times A_{2} \rightarrow A_{2}$ be the retracting homotopy that shows $B$ as a deformation retract of $A_{2}$. Define the functions

$$
\begin{align*}
& \mathcal{F}:[0,1] \times A_{2} \rightarrow A_{1} \cup_{f} A_{2} \quad: \quad \mathcal{F}(t,-)=F \circ R(t,-)  \tag{2.4.6}\\
& \mathcal{I}:[0,1] \times B \rightarrow A_{1} \cup_{f} A_{2}: \quad: \quad \mathcal{I}(t,-)=I \tag{2.4.7}
\end{align*}
$$

then by definition $\mathcal{F}(t,-) \circ i=\mathcal{I}(t,-) \circ f$. So the following square commutes

and so there is an unique homotopy $H:[0,1] \times\left(A_{1} \cup_{f} A_{2}\right) \rightarrow A_{1} \cup_{f} A_{2}$ such that

$$
\begin{equation*}
H(t,-) \circ F=\mathcal{F}(t,-) \wedge H(t,-) \circ I=\mathcal{I}(t,-) \tag{2.4.9}
\end{equation*}
$$

It's easy to check that by definition of $\mathcal{F}$ and $\mathcal{I}$ we have

$$
\begin{equation*}
H(0,-)=\operatorname{Id}_{A_{1} \cup_{f} A_{2}} \wedge H\left(1, A_{1} \cup_{f} A_{2}\right)=A_{1} \cup_{f} B \tag{2.4.10}
\end{equation*}
$$

and so we produced a retracting homotopy showing $A_{1} \cup_{f} B$ as a deformation retract of $A_{1} \cup_{f} A_{2}$.

Corollary 2.4.5. In the previous theorem, if we take $B$ to be just $A_{0}$ we obtain that whenever $A_{0}$ is a deformation retract of $A_{2}$, then $A_{1}$ is a deformation retract of $A_{1} \cup_{f} A_{2}$. Corollary 2.4.6. A map $f: A_{0} \rightarrow A_{1}$ is a homotopy equivalence if and only if $A_{0}$ is a deformation retract of $M(f)$.

Theorem 2.4.7. Given $A_{1}^{\prime} \subseteq A_{1}$ and $A_{2}^{\prime} \subseteq A_{2}$ such that $A_{0} \subseteq A_{2}^{\prime}$ and $f\left(A_{0}\right) \subseteq A_{1}^{\prime}$, if we call $g$ the restriction of $f$ to all and only the elements that are sent in $A_{1}^{\prime}$, then we have that $A_{1}^{\prime} \cup_{g} A_{2}^{\prime}$ is a subspace of $A_{1} \cup_{f} A_{2}$.

Corollary 2.4.8. In the notations used throughout this chapter $M(f) \cup A_{2}$ is a subspace of $M(F)$. So call $j: M(f) \cup A_{2} \rightarrow M(F)$ the inclusion and $q: M(F) \rightarrow A_{1} \cup_{f} A_{2}$ the canonical deformation retraction. Then, if the inclusion of $A_{0}$ into $A_{2}$ is a cofibration, the map

$$
\begin{equation*}
p=q \circ j: M(f) \cup A_{2} \rightarrow A_{1} \cup_{f} A_{2} \tag{2.4.11}
\end{equation*}
$$

is a homotopy equivalence rel $A_{1}$.

### 2.5 Van Kampen theorem for the fundamental groupoid

We're now about to prove the main result of our work: we will generalize what we did in section 1.5 to a more general case and will so prove Van Kampen's theorem.

Theorem 2.5.1 (Van Kampen's theorem). We're in the usual setup of adjunction spaces

and we have a set $C \subseteq A_{2}$ that is representative in $A_{2}$ and $A_{0}$ and a set $D \subseteq A_{1}$ representative in $A_{1}$ such that the restriction $g$ of $f$ to $A_{2} \cap C$ has values in $D$; we call $B=D \cup_{g} C$ and $A=D \cup C$. We switch from the square (2.5.1) to the square of fundamental groupoids, constrained by $C$ and $D$ :

and we claim that this square commutes if and only if the morphism (induced by the one built in corollary 2.4.8)

$$
\begin{equation*}
p_{\text {ind }}: \pi\left(M(f) \cup A_{1}, A\right) \rightarrow \pi\left(A_{1} \cup_{f} A_{2}, B\right) \tag{2.5.3}
\end{equation*}
$$

is a homotopy equivalence between these two fundamental groupoids.
Proof. The main idea is to take appropriate spaces such that it will be possible to apply theorem 1.5.15. So we choose:

$$
\begin{align*}
& X=M(f) \cup A_{2}  \tag{2.5.4}\\
& X_{1}=M(f)  \tag{2.5.5}\\
& X_{2}=X-A_{1}  \tag{2.5.6}\\
& X_{0}=X_{1} \cap X_{2}  \tag{2.5.7}\\
& Y=D \cup\left(C-A_{0}\right) \tag{2.5.8}
\end{align*}
$$

that satisfies the required hypothesis, since $\dot{X}_{1}$ and $\dot{X}_{2}$ cover $X$. So, by theorem 1.5.15 we have that $p$ sends $D \cup_{g} C$ into $D \cup\left(C-A_{0}\right)$ bijectively. In our new simplified notations, this means that there is a bijection $B \leftrightarrow Y$. Now notice that $D$ is representative in $A_{1}$ and so it is in the mapping cylinder $X_{1}=M(f)$ of $f: A_{0} \rightarrow A_{1}$. Also, $Y \supseteq D$, so it meets at least the same path-connected components that $D$ meets and so it is representative in the same sets. Finally, $C$ is representative in $A_{0}$ so of course is $C \cap A_{0}$ and each of its points can be sent into a point of $D$ via the segments that make up
the mapping cylinder $M(f)$. By construction of the mapping cylinder if we call $s_{c}$ the segment that sends $c \in C \cap A_{0}$ down the mapping cylinder to a point of $D$, we have that $p_{\text {ind }}\left(\left[s_{c}\right]\right)=\operatorname{Id}_{[f(c)]}$. We can compose the two horizontal arrows in the square given by 1.5 .15 in (1.5.23) and obtain the pushout

then, if we call for short $Q=A_{1} \cup_{f} A_{2}$ we can extend this square via $p$ and canonical isomorphisms induced by the homotopy equivalences (using the fact that so is $p_{\text {ind }}$ when restricted to $\left.p_{\simeq}: \pi\left(X_{1}, Y\right) \rightarrow \pi\left(A_{1}, D\right)\right)$ into

where $p_{r}$ is the restriction of $p_{\text {ind }}$ to $\pi(X, Y)$. As it's easy to check, because of the properties of $s_{c}$ this box commutes. As it's clear from the picture, to determine an isomorphism from the "new" front square to the "old" back square is sufficient and necessary (s.a.n.) that $p_{r}$ is an isomorphism itself. On the objects we don't have any problem since $p_{r}$ is bijective. So we can affirm that the s.a.n. condition is that $p_{r}: \pi(X, Y) \rightarrow \pi(Q, B)$ is an homotopy equivalence. But now notice that we can remove the restricting constraint and affirm that the it's the same to request the whole $p_{\text {ind }}: \pi(X, A) \rightarrow \pi(Q, B)$ to be an homotopy equivalence, since trivially $\pi(X, Y)$ is a deformation retract of $\pi(X, A)$ because a path in $\pi(X, Y)$ is a path in $\pi(X, A)$ and so we have an isomorphism of groupoids that is given by the inclusion in one way and by the retraction in the other. So, bringing all the ideas together, we know that (2.5.9)

- that is the front square of the box - is a pushout and so (2.5.1) - that is the back square of the box - is a pushout too if we can establish an isomorphism between these two square and we proved that this is the case if and only if $p_{\text {ind }}$ is a homotopy equivalence.

Corollary 2.5.2. If the inclusion of $A_{0}$ in $A_{2}$ is a cofibration, then 2.5.2 is a pushout. Proof. It immediately follows from corollary 2.4.8.

Corollary 2.5.3. If $A_{1}$ and $A_{2}$ are such that they are closed subsets of $A_{1} \cup A_{2}$ and the inclusion of $A_{1} \cap A_{2}$ is cofibered in $A_{1}$, then by taking $B$ representative in $A_{1}, A_{2}$ and $A_{1} \cap A_{2}$ and letting $f$ be just the inclusion, by theorem 2.5.1 it just follows that the following squares (where all the arrows are naturally induced by the inclusions) is a pushout:


Corollary 2.5.4. In the same hypothesis of corollary 2.5.3, if $\pi\left(A_{1} \cap A_{2}, B\right)$ is discrete then

$$
\begin{equation*}
\pi\left(A_{1} \cup A_{2}, B\right) \simeq \pi\left(A_{1}, B\right) * \pi\left(A_{2}, B\right) \tag{2.5.12}
\end{equation*}
$$

Proof. Just notice that from () being a pushout it follows that the canonical morphism from $\pi\left(A_{1}, B\right) \sqcup \pi\left(A_{2}, B\right)$ to $\pi\left(A_{1} \cup A_{2}, B\right)$ is universal.

Corollary 2.5.5. In the same hypothesis of corollary 2.5.2, if $\pi\left(A_{1}, D\right)$ and $\pi\left(A_{2}, C\right)$ are discrete, $C \subseteq Y$ and $f(C)=B=D$ then the morphism $F$ of (2.5.1) is universal.

Proof. In this case the hypothesis we imposed and the fact that (2.5.1) is a pushout just fulfill the definition of universal morphism.
action of a group, 38
action of a groupoid, 30
adjunction space, 20
annihilation, 40
$\mathbf{C}_{\square}, 21$
category, 2
axioms, 2
dual, 16
full, 4
product of, 15
subcategory, 4
wide, 4
co-retraction, 4
cofibration, 31
component, 11
composite, 20
connected groupoid, 10
contractible space, 26
contravariant functor, 16
coproduct, 18
deformation retract, 41
deformation retraction
of a category, 27
of a space, 41
discrete graph, 36
dual category, 16
epimorphism, 5
equivalence of categories, 24
fibration, 29
final object, 5
free groupoid, 37
free product, 38
full subcategory, 4
full subgraph, 37
functor, 13
contravariant, 16
functor category, 24
fundamental group, 10
fundamental groupoid, 9
1-connected, 10
simply-connected, 10
graph, 36
discrete, 36
full, 37
subgraph, 37
wide, 37
graph morphism, 37
group, 10
action, 38
object group, 11
groupoid, 8
action, 30
component, 11
connected, 10
free, 37
free product, 38
quotient, 40
subgroupoid, 8
track groupoid, 31
tree groupoid, 12
universal, 34
homotopic spaces, 26
homotopy
of categories, 24
of maps, 30
rel a subcategory, 27
rel endmaps, 31
rel endpoints, 8
homotopy equivalence, 26
homotopy extension property, 31
homotopy type, 26
initial object, 5
isomorphic objects, 5
isomorphism, 4
mapping cylinder, 42
monomorphism, 5
morphism, 2
of graphs, 37
universal, 36
natural equivalence, 24
natural transformation, 23
normal subgroupoid, 40
object, 2
object group, 11
pointed space, 15
pushout, 19
quotient groupoid, 40
representative set, 22
retracting homotopy, 41
retraction, 4
square of a space, 22
subcategory, 4
subgraph, 37
subgroupoid, 8
generated by a graph, 37
normal, 40
track groupoid, 31
tree groupoid, 12
universal groupoid, 34
universal morphism, 36
wide subcategory, 4
wide subgraph, 37
word, 34
zero object, 5

## BIBLIOGRAPHY

[1] J. Adamek, H. Herrlich, and G.E. Strecker. Abstract and Concrete Categories: The Joy of Cats. Dover Publications, 2009.
[2] R. Brown. Topology and groupoids. www.groupoids.org, 2006.
[3] S. MacLane. Groups, categories and duality. Proceedings of the National Academy of Sciences of the United States of America, 34(6):263, 1948.


[^0]:    ${ }^{1}$ Watch the video at http://www.youtube.com/watch?v=nLcr-DWVEto.

