Exact Prediction and Universal Coding for Trees

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Abstract — No closed formula for the optimal predictor (estimator) exists for the model of order preserving distributions on a finite tree. We present an algorithm of low complexity for a large class of trees.

Let $T = (T, \leq)$ be a finite rooted tree and consider the model \mathcal{P} of all distributions over the nodes of T which respect the ordering $(P \in \mathcal{P} \text{ means } P(a) \leq P(b)$ whenever $a \leq b$ – hence the root has minimal, the leaves maximal probability). For the unique *optimal predictor* $P^* \in \mathcal{P}$, $\sup_{P \in \mathcal{P}} D(P || P^*)$ is minimal among all distributions in \mathcal{P} . It is our goal to determine P^* exactly.

Presently, results in this direction (exact rather than numerical or asymptotic results) are somewhat sporadic. The starting point of exact results of the type here considered is Ryabko [1]. The author, jointly with Peter Harremoës, has pointed to exact results for Bernoulli sources, cf. [3]. In [2] numerical methods are indicated, but based on the same theoretical reasoning as here (and with some associated exact results, not stated there). As a distant goal we mention the possibility to base asymptotically optimal prediction for, say Bernoulli sources on exact prediction results.

Our concern here is a case-study: No side information, models defined via a tree structure on the basic alphabet, taken finite. Even so, the problem is complicated and to further simplify, we limit the discussion: For a sequence $\mathbf{k} = (k_1, \ldots, k_n)$ of natural numbers, $T = T[\mathbf{k}]$ denotes the rooted tree with k_1 branches emerging from the root, with k_2 branches emerging from each node in level 1 etc. until k_n nodes emerging from each node in level n - 1. Trees of this type have uniform branching and \mathbf{k} is the branching pattern.

Fig. 1: Trees with optimal weights and marking of active anchors

The figure depicts the trees T[1, 1], T[2, 2] and T[1, 2]. For each of them, the optimal predictor is indicated by showing the weights assigned to each node. The last example is a bit surprising in that the root and its immediate successor are assigned the same weight, hence the same probability. The marked nodes show the *spectrum* $\sigma(T)$ of the trees. $\sigma(T)$ consists of the *active anchors*, nodes *a* for which the uniform distribution over $\{b|b \ge a\}$ contributes to the optimal predictor (i.e., the uniform distribution has positive weight in the unique convex combination representing P^*). For the two first examples, $\sigma(T) = T$ but for the last one, there is an inactive node. This phenomenon accounts for the contra-intuitive feature that nodes in different levels may have the same weight.

The key difficulty is the determination of $\sigma(T)$. Once known, it is easy to calculate P^* exactly. If $k_1 \ge \cdots \ge k_n$, then $\sigma(T) = T$, and the tree is *balanced*. The case $k_1 = \cdots = k_n = 1$ then essentially is Ryabko's result, [1].

For the general tree $T = T[\mathbf{k}]$ we base the analysis on the quantities $T_{i,j}, N_i, [i, j], \sigma_i, \alpha_i$ and ν defined as follows: $T_{i,j} = \prod_{i+1}^{j} k_t$ (with special cases given by T(i, i) = 1 and T(i, n + 1) = 0), $N_i = \sum_{i=1}^{n} T(i, j)$,

$$[i,j] = \frac{\bar{N}_i - T_{i,j+1}\bar{N}_{j+1}}{N_i - T_{i,j+1}N_{j+1}} \text{ for } 0 \le i \le j \le n$$

(with $\bar{a} = a \ln a$), $\sigma_n = n$,

$$\sigma_i = \min\{j \ge i | [i, j] \ge [j + 1, \sigma_{j+1}]\}$$
 for $i = n - 1, \dots, 0$

and, finally, ν and α 's are defined by $\alpha_0 = 0$, $\alpha_{i+1} = \sigma_{\alpha_i}$ for $0 \le i < \nu$ and $\alpha_{\nu} = n$.

Theorem. The spectrum $\sigma(T)$ consists of all nodes which lie in one of the levels $\alpha_0, \dots, \alpha_{\nu}$. For $0 \leq i \leq \nu$, the optimal predictor assigns the probability

$$\frac{e^{-[\alpha_i,\sigma_{\alpha_i}]}}{Z},$$

to all nodes in the levels $\alpha_i, \dots, \sigma_{\alpha_i}$. Here, Z is a normalization factor.

Special structure guarantees that the algorithm is of low complexity. In fact, the maximal number of comparisons necessary (to determine the σ 's) is 2n-3 for any branching pattern of length n. The author looks forward to present orally facts about the algorithm which, more understandable than by a series of definitions and formulas as here, will reveal the true nature of the algorithm. As we shall see, this depends on a set of combinatorial identities.

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References

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